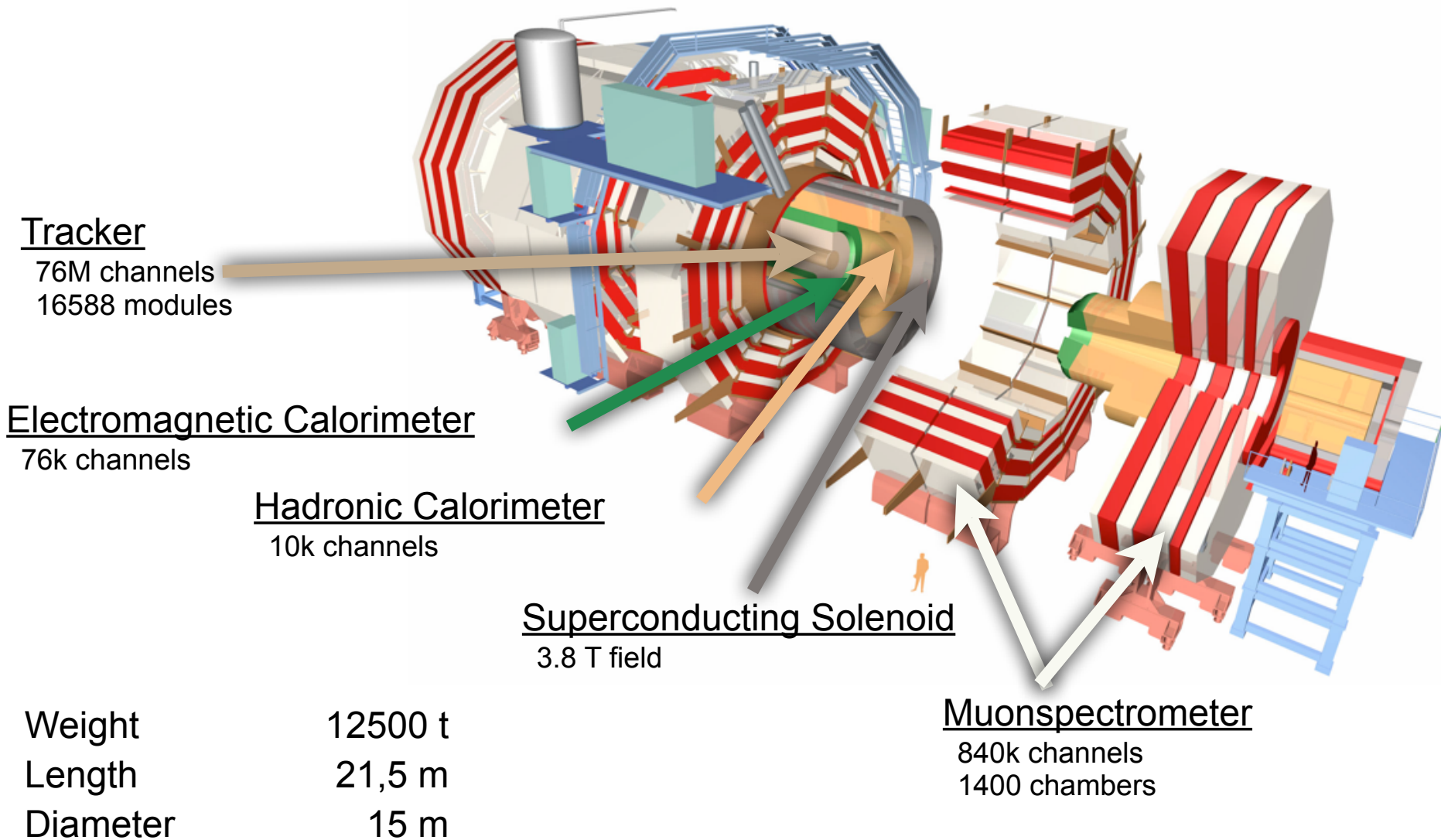


The Upgrade of the CMS Tracker for the HL-LHC

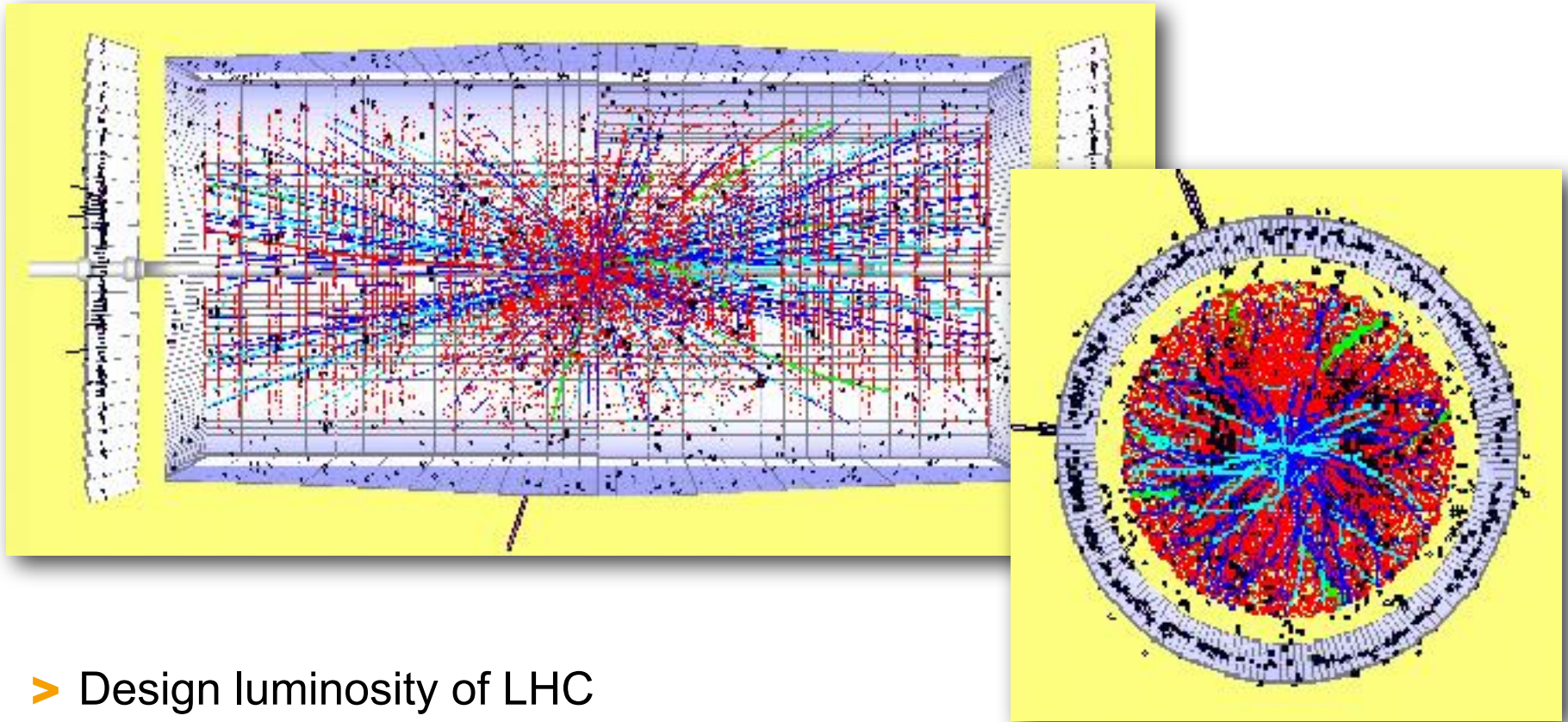


Andreas Mussgiller
DPG Tagung Göttingen
1 März 2012

The CMS Experiment at LHC

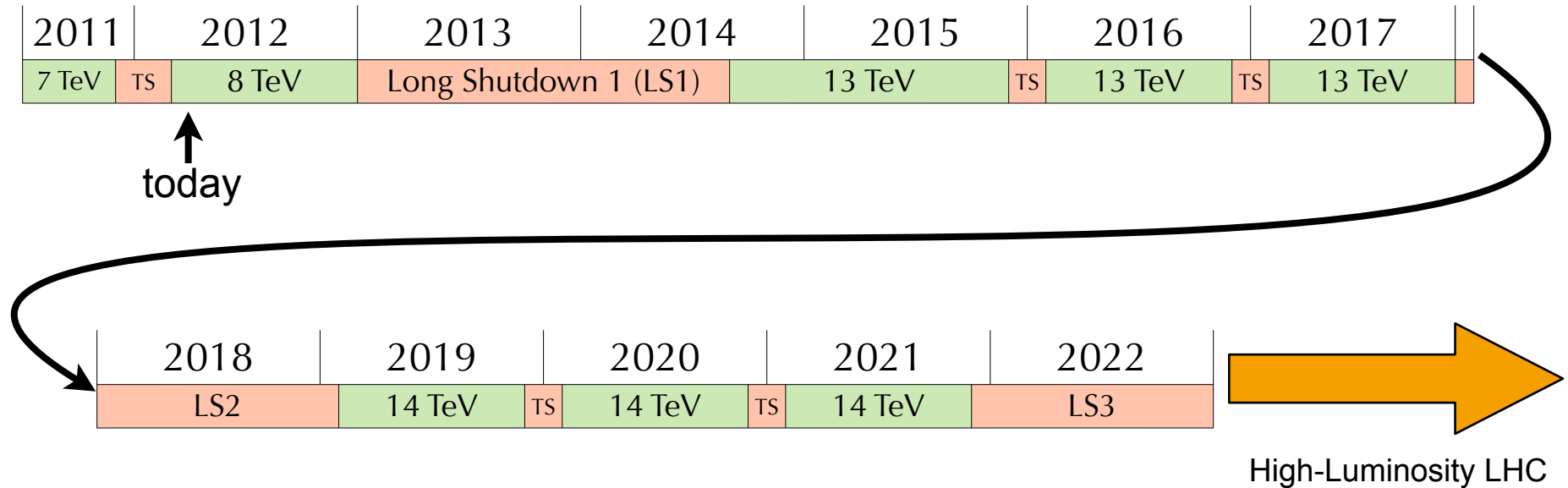


Event at a Luminosity of $10^{34} \text{ cm}^{-2}\text{s}^{-1}$



- Design luminosity of LHC
- Limit of the current tracker
 - would become inefficient for higher luminosity
- Peak luminosity for 7 TeV running is $3.5 \cdot 10^{33} \text{ cm}^{-2}\text{s}^{-1}$

Preliminary LHC 10 Year Plan



- > Several upgrades planned for LS1 and LS2
- > High-luminosity LHC era starts in 2023
- > Expect $5 \cdot 10^{34} \text{ cm}^{-2}\text{s}^{-1}$ delivered to CMS
- > CMS will install a new and improved tracker during LS3



Requirements to the future CMS Tracker

- > Higher granularity to deal with increased occupancy
 - Modules will have shorter strips
- > Tracker must provide trigger to be used in the Level-1 trigger
 - Input rate to Level-1 trigger needs to stay below 100kHz
- > Higher power consumption in the front-end requires new powering scheme
 - DC/DC conversion close to or on the modules
 - Less resistive losses
- > Use radiation hard sensor material
- > Sensors must be kept below -20°C
 - Switch to evaporative CO₂ cooling
 - Need an excellent design to have sufficient cooling while having low mass
- > Reduce the material budget
 - Current tracker is rather heavy
 - A performance limitation of the existing tracker

T63.7

T63.9

T63.10

T67.3

T69.5

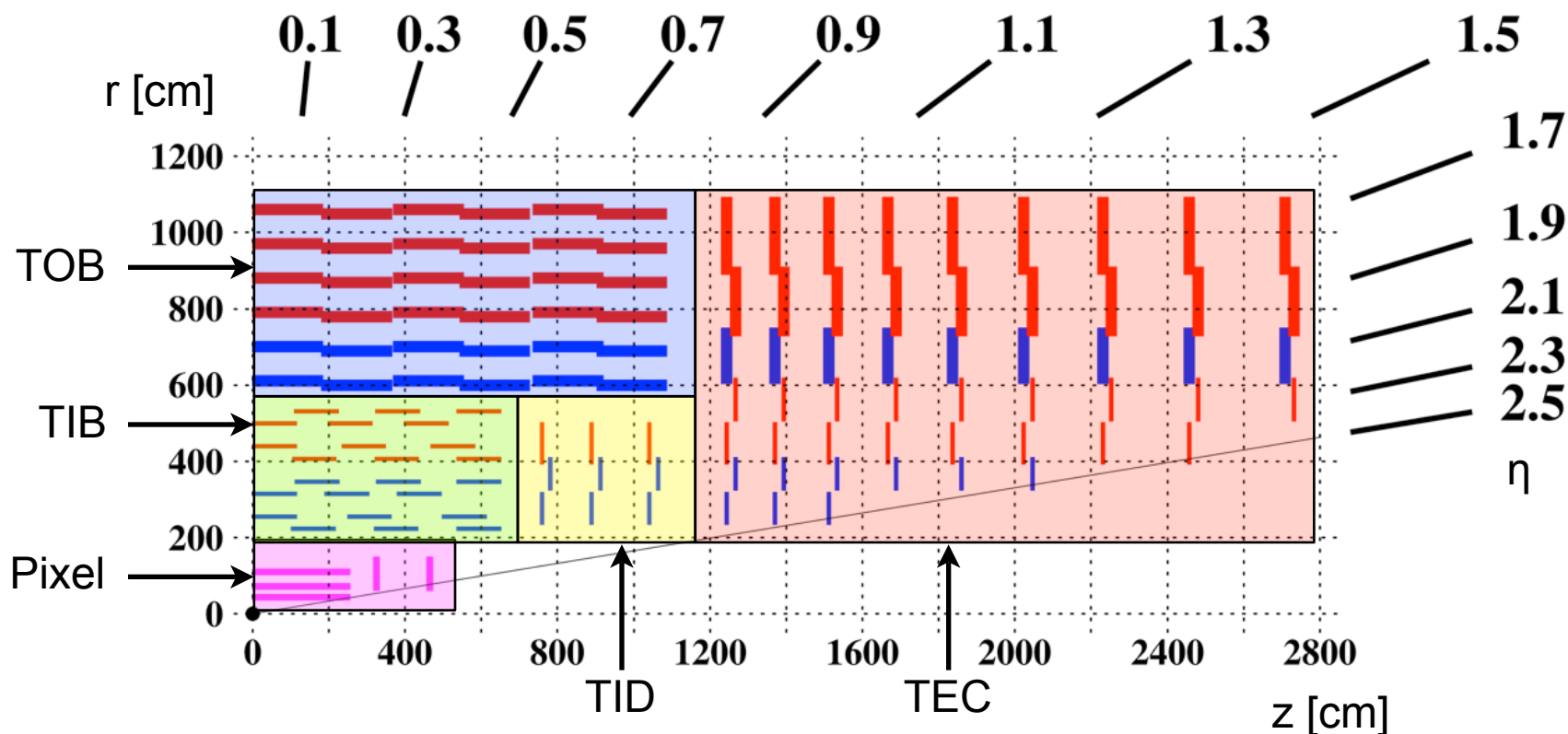


Outline

- > Overview of considered module types
- > Layout of the future tracker
- > Finite element analyses of modules
 - thermal
 - thermo-mechanical
- > Measurements
- > Outlook



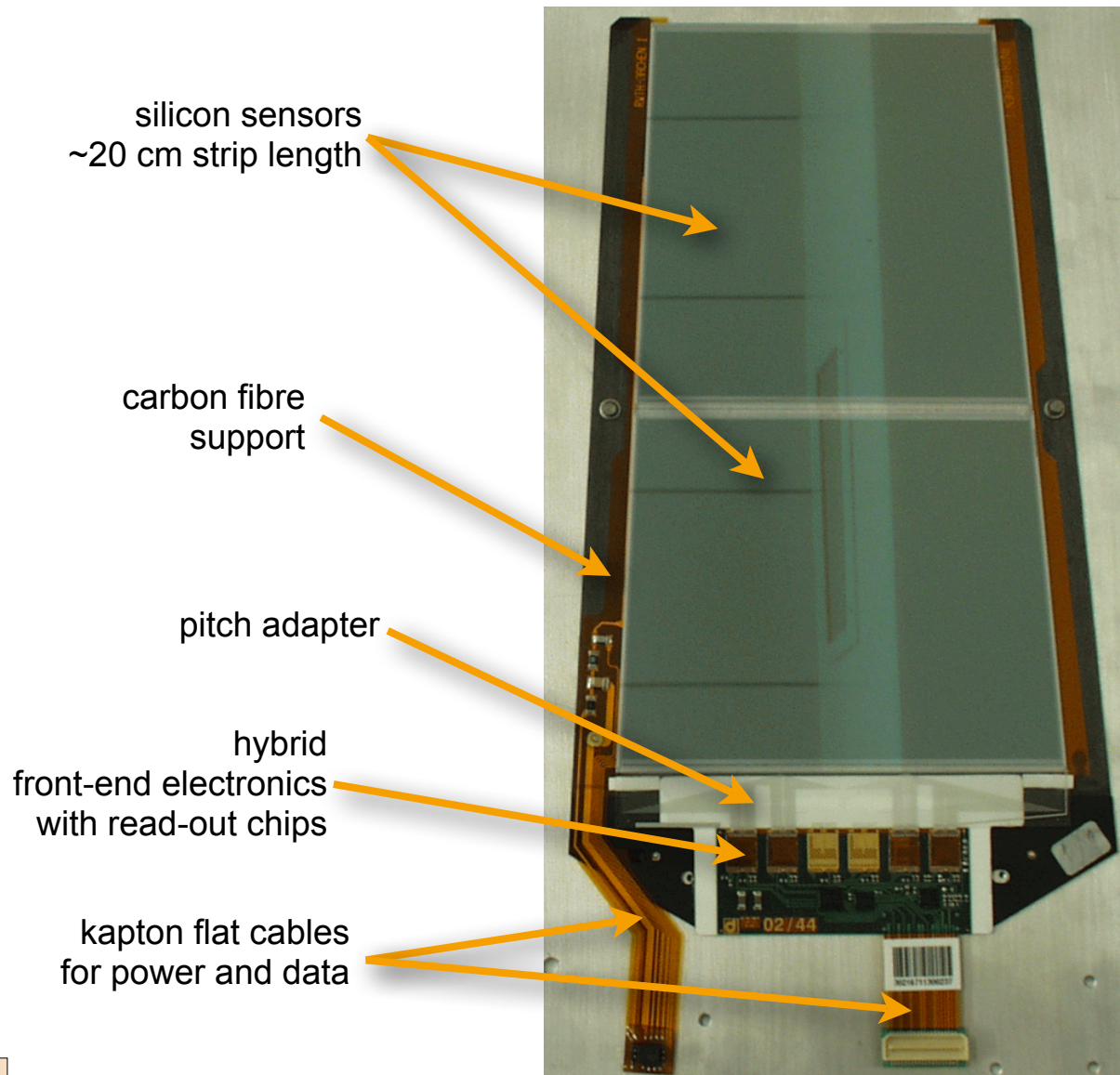
Layout of the current Tracker



- > 15148 modules (excluding pixel detector)
- > 27 different module types



Current TEC Module



Concept of the future Modules

- > Modules will provide trigger signal for high p_T tracks

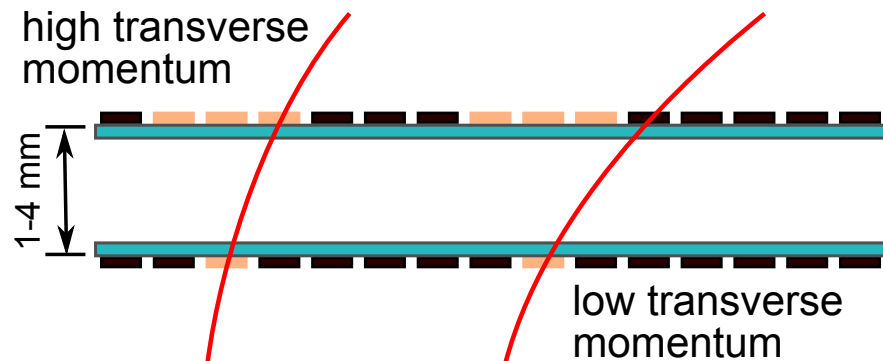
- will be used in the Level-1 trigger system

- > Each module will consist of two sensors at a distance of 1 - 4 mm

- strong magnetic field of CMS allows for a measurement of p_T on the module
- hits in both sensors are correlated
- matching hits have to be within a search window
- distance between sensors depends on module position (r and η)

- > Increase granularity, i.e. shorter strips

- read out at both ends of the strip

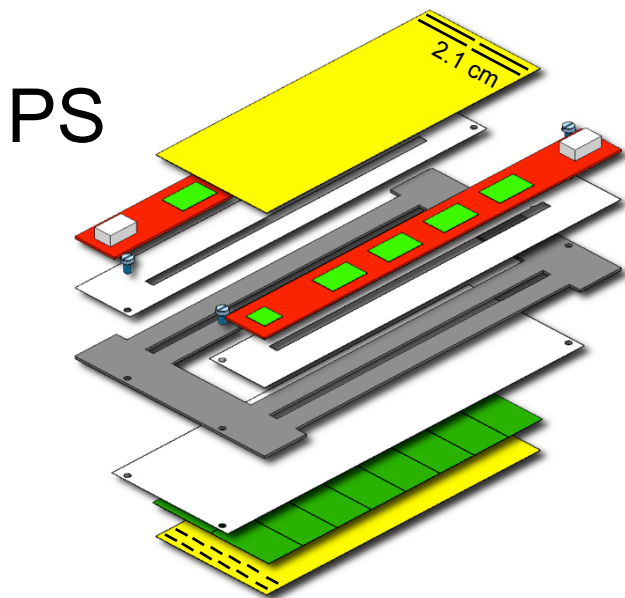


- > Only two different module types throughout the tracker

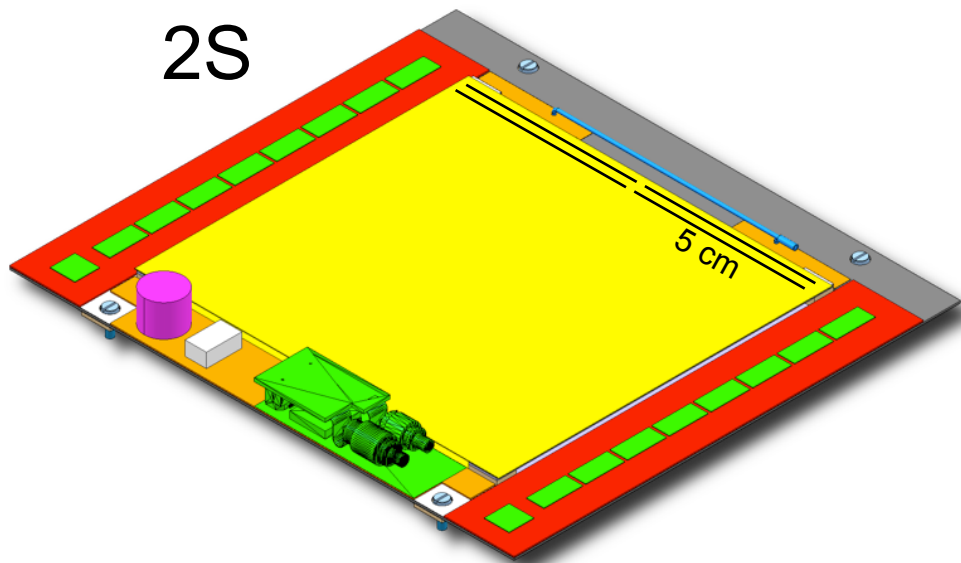
- with a few different sensor spacings
- makes the module design much more easy



Considered Module Designs



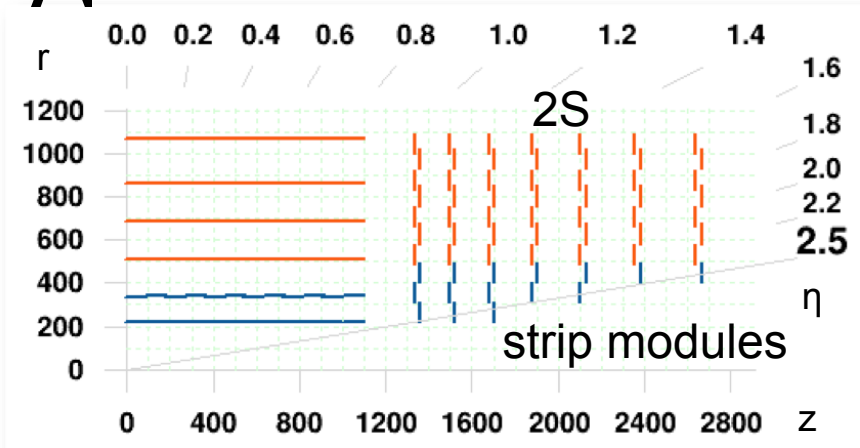
- > Sandwich of a pixel and strip sensor
 - 4.2 cm x 9.4 cm active area
 - 2.1 cm long strips (100 μm pitch)
 - 1.5 mm x 100 μm pixels
- > Trigger capability implemented in pixel read-out chips
- > Provides 2D information



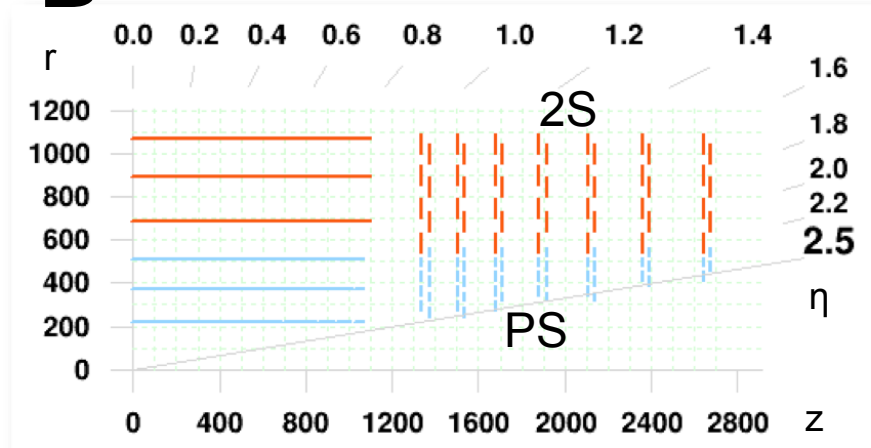
- > Sandwich of two strip sensors
 - 10 cm x 9.2 cm active area
 - 5 cm long strips (90 μm pitch)
- > Trigger capability implemented in read-out chips
 - CMS Binary Chip under development in the UK

Tracker Layout Options

A barrel & end-cap design



B barrel & end-cap design



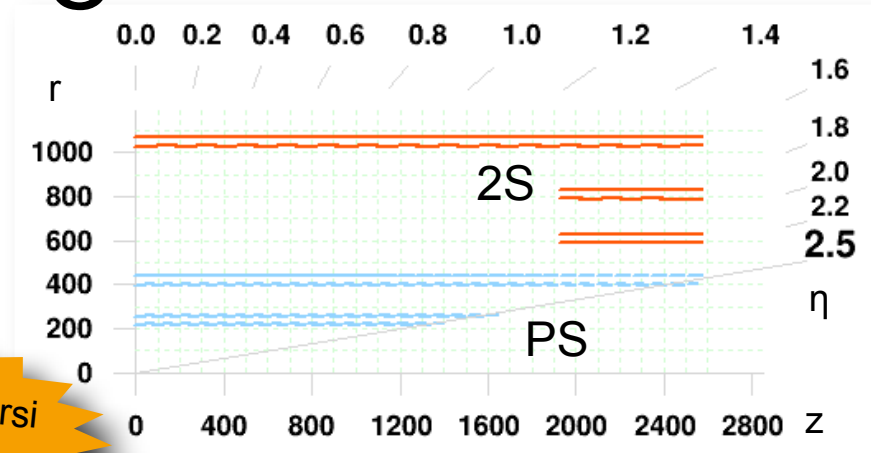
> A: standard strip modules at $r < 50$ cm

> B & C

- PS modules at $r < 50$ cm
- 2S modules at $r > 50$ cm

> More design options under investigation

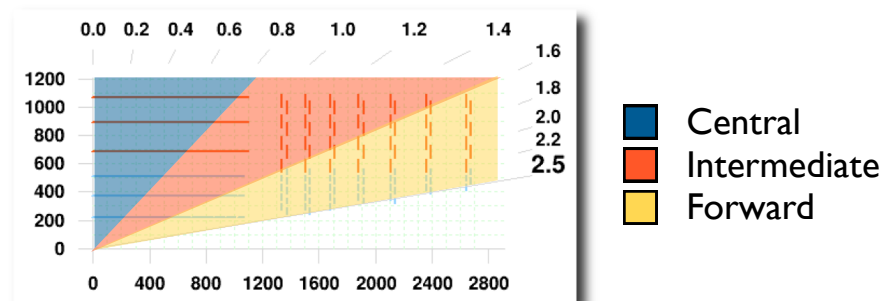
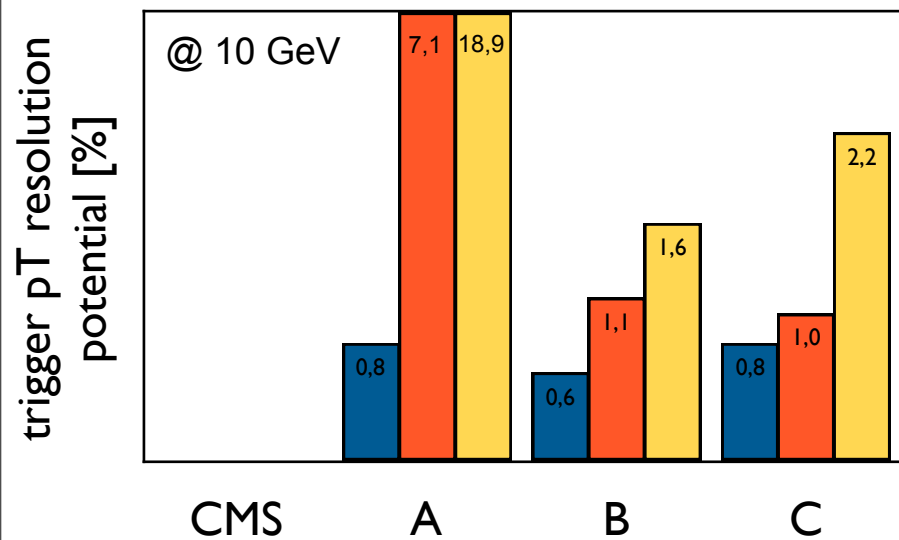
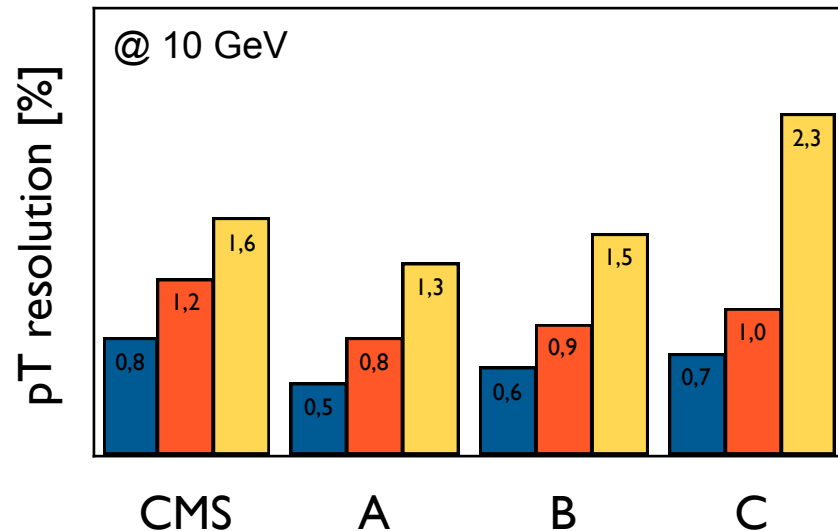
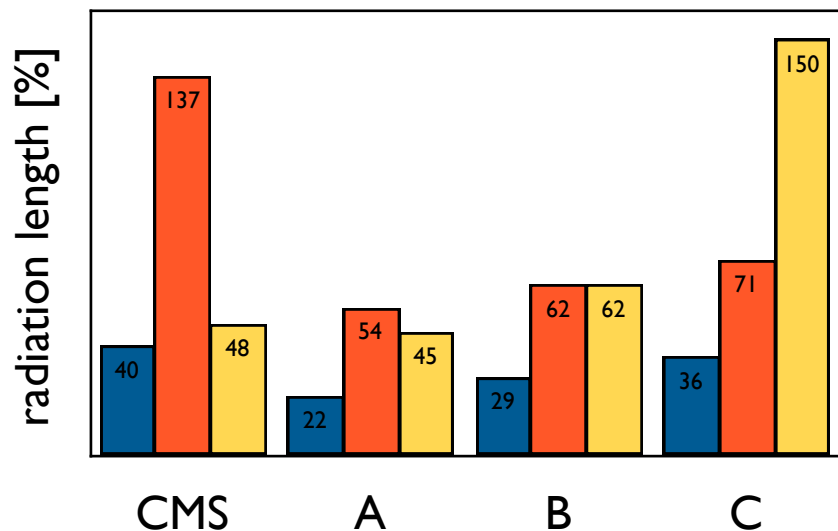
C long barrel design



Studies by S. Mersi
et al. (CERN)



Layout Comparison

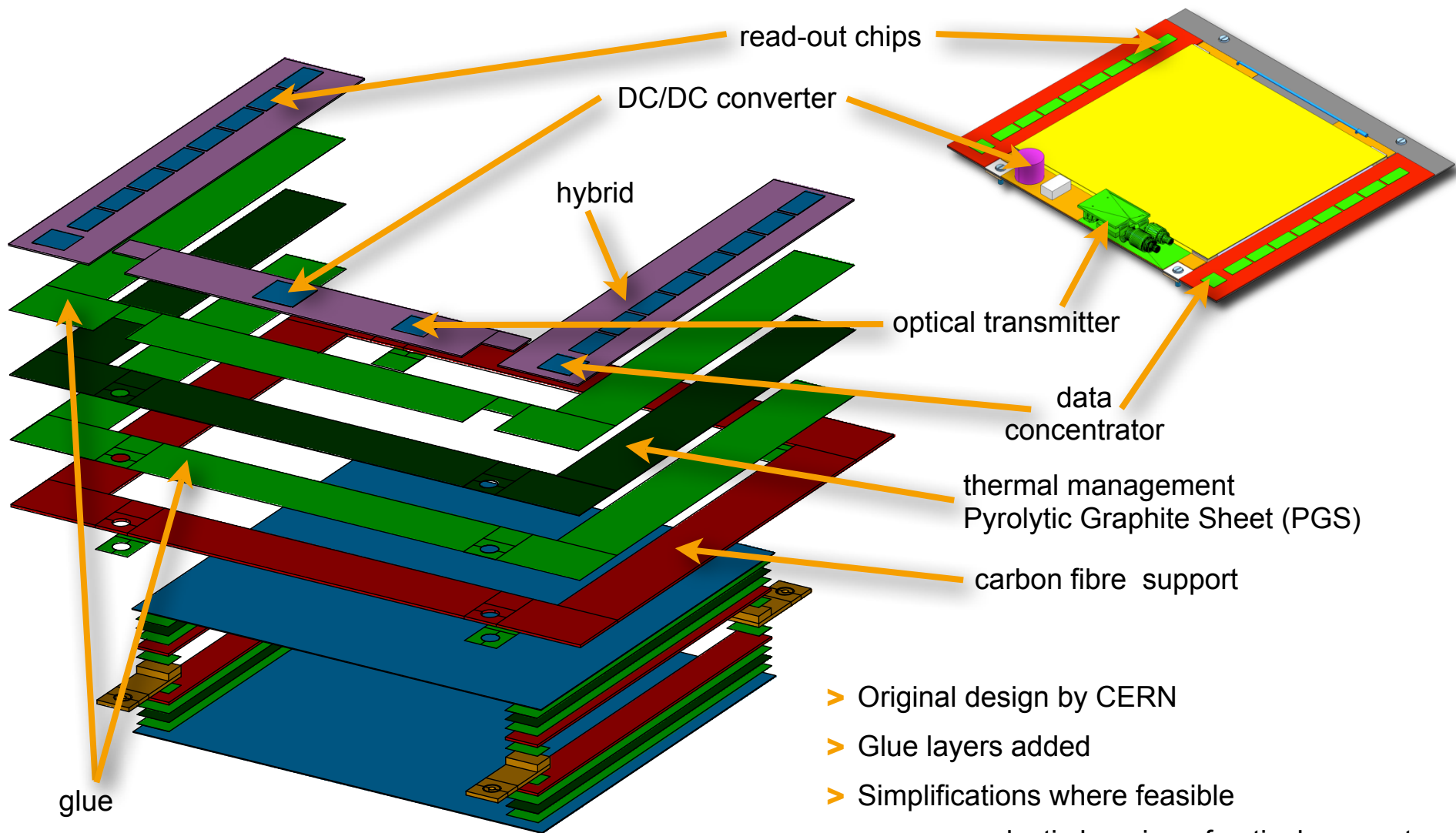


➤ Preliminary result suggests layout with PS and 2S modules in a barrel & end-cap configuration (B)

- low material budget
- good tracking and trigger performance

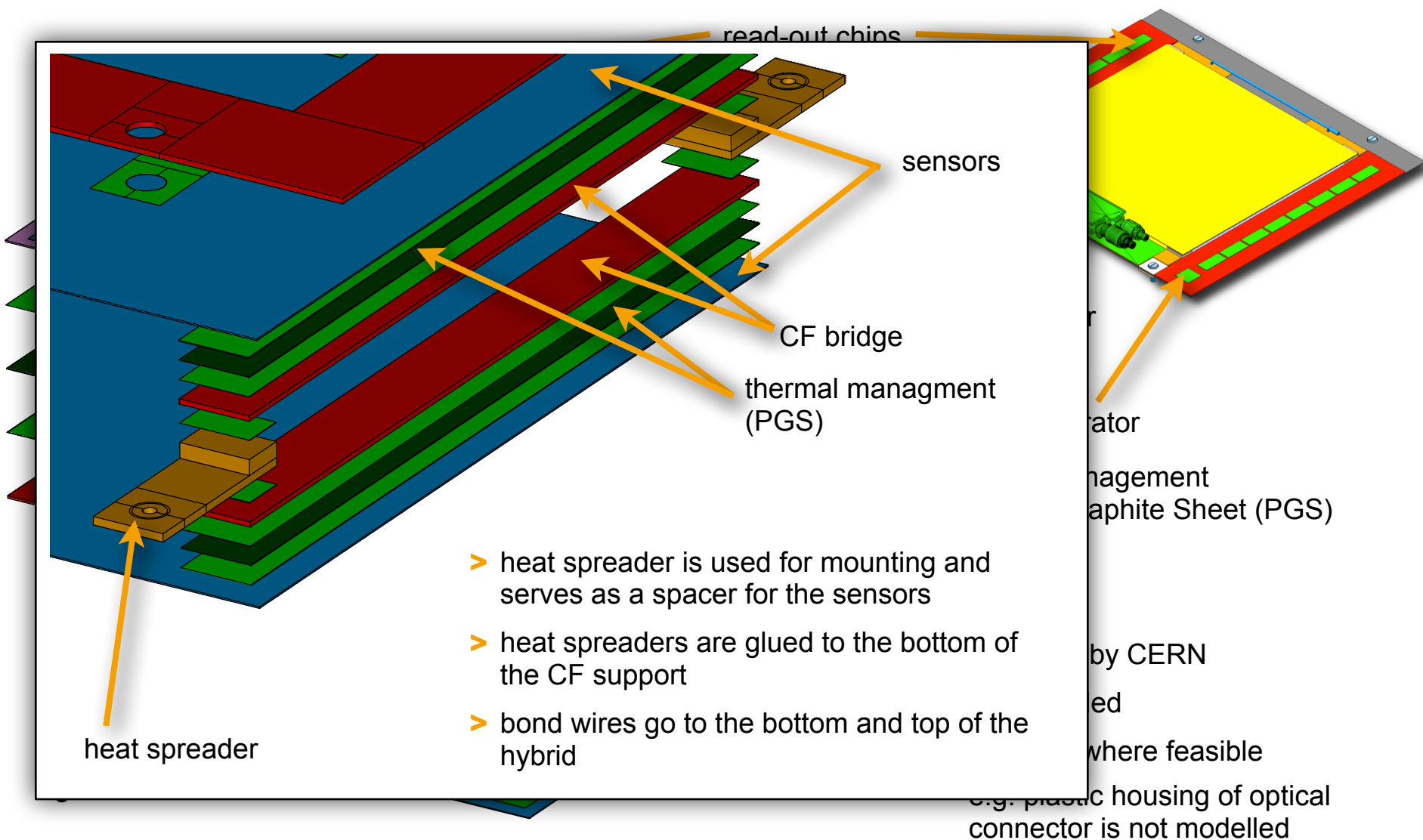


Finite Element Model of the 2S Module

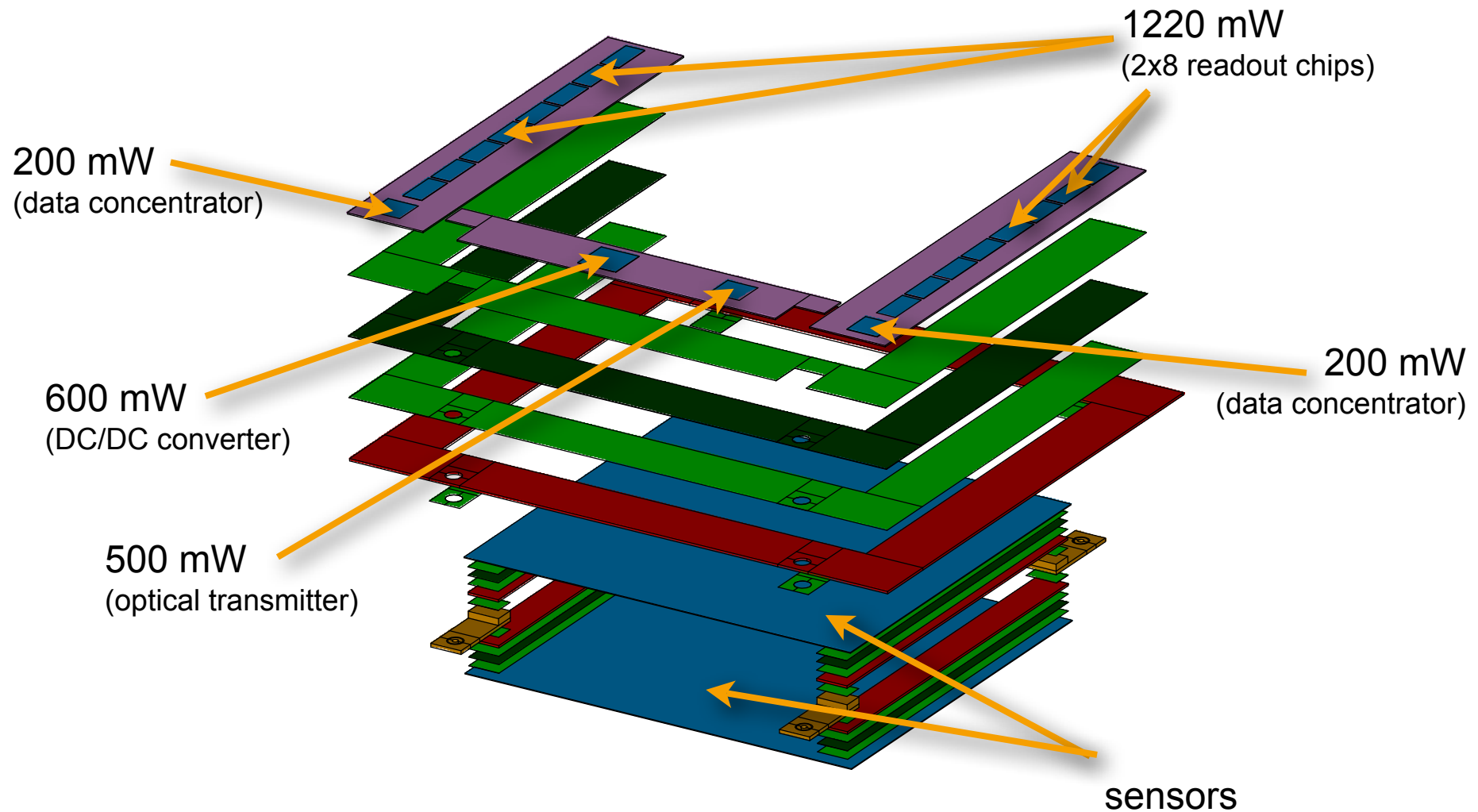


- > Original design by CERN
- > Glue layers added
- > Simplifications where feasible
 - e.g. plastic housing of optical connector is not modelled

Finite Element Model of the 2S Module (cont.)



Thermal Loads



➤ Total power of front-end electronics: 2.72 W

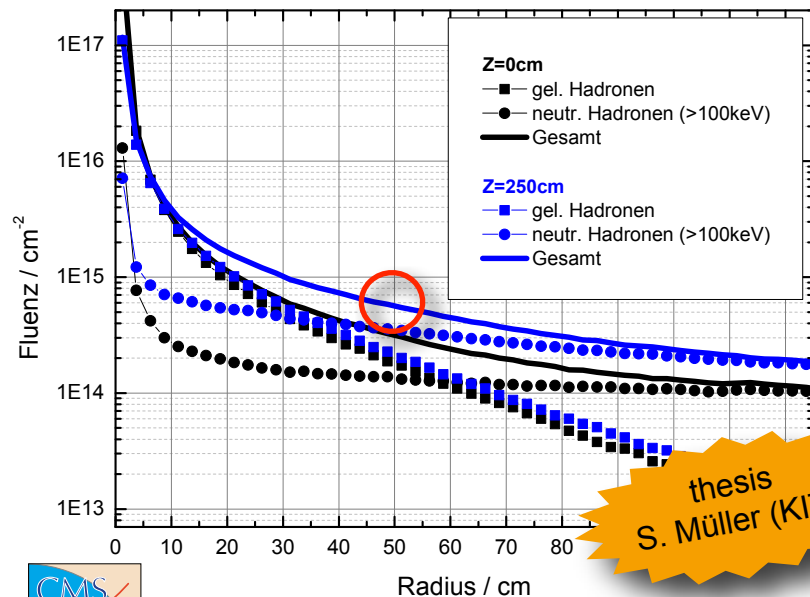
Thermal Loads - Sensors

- Power consumption of sensors depend on temperature and radiation damage
 - Use maximum fluence for a given module type and 3000 fb⁻¹: $\Phi = 5.5 \cdot 10^{14} \text{ 1/cm}^2$
 - Leakage current at RT: $I = 5.5 \cdot 10^{14} \text{ 1/cm}^2 \times 1.84 \text{ cm}^3 \times 4.0 \cdot 10^{17} \text{ A/cm} = 35.4 \text{ mA}$

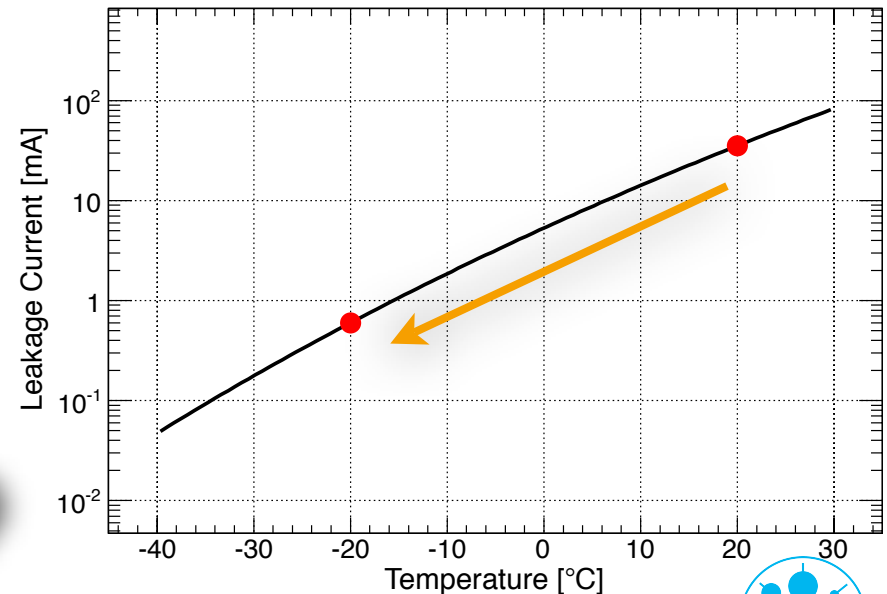
$\uparrow$
fluence

$\uparrow$
volume

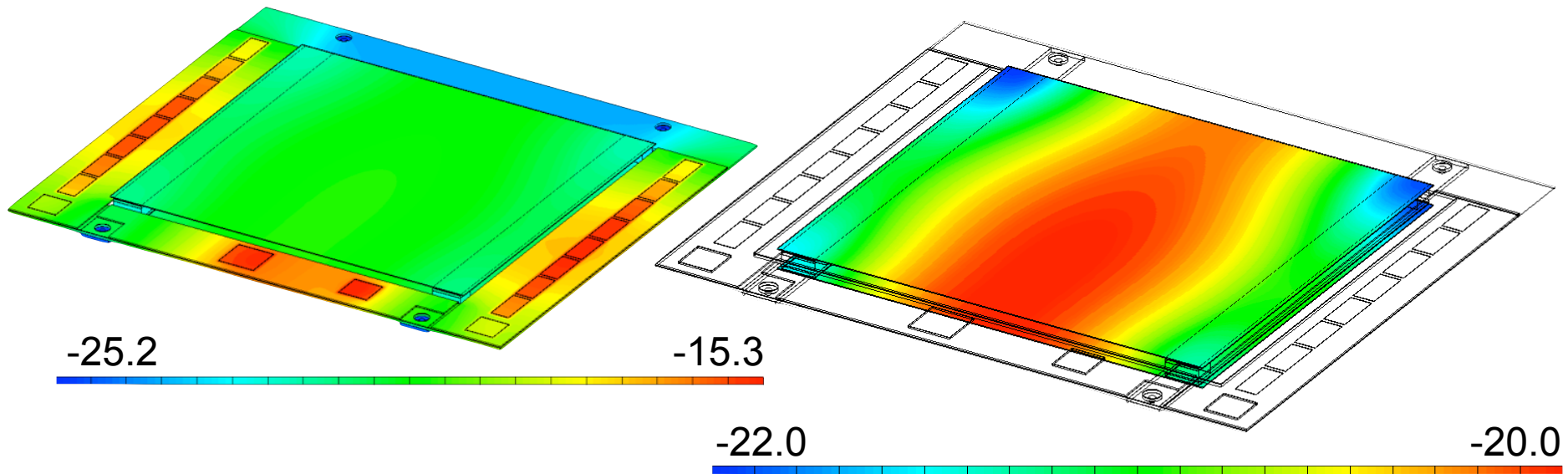
$\uparrow$
damage constant
 - Scale leakage current to -20°C: $I \propto (kT)^2 \exp\left(-\frac{1.21 \text{ eV}}{kT}\right) \Rightarrow I = 0.60 \text{ mA}$
 - $P = 0.60 \text{ mA} \times 600 \text{ V} = 360 \text{ mW}$
- Total power consumption by module: 3.44 W



thesis
S. Müller (KIT)



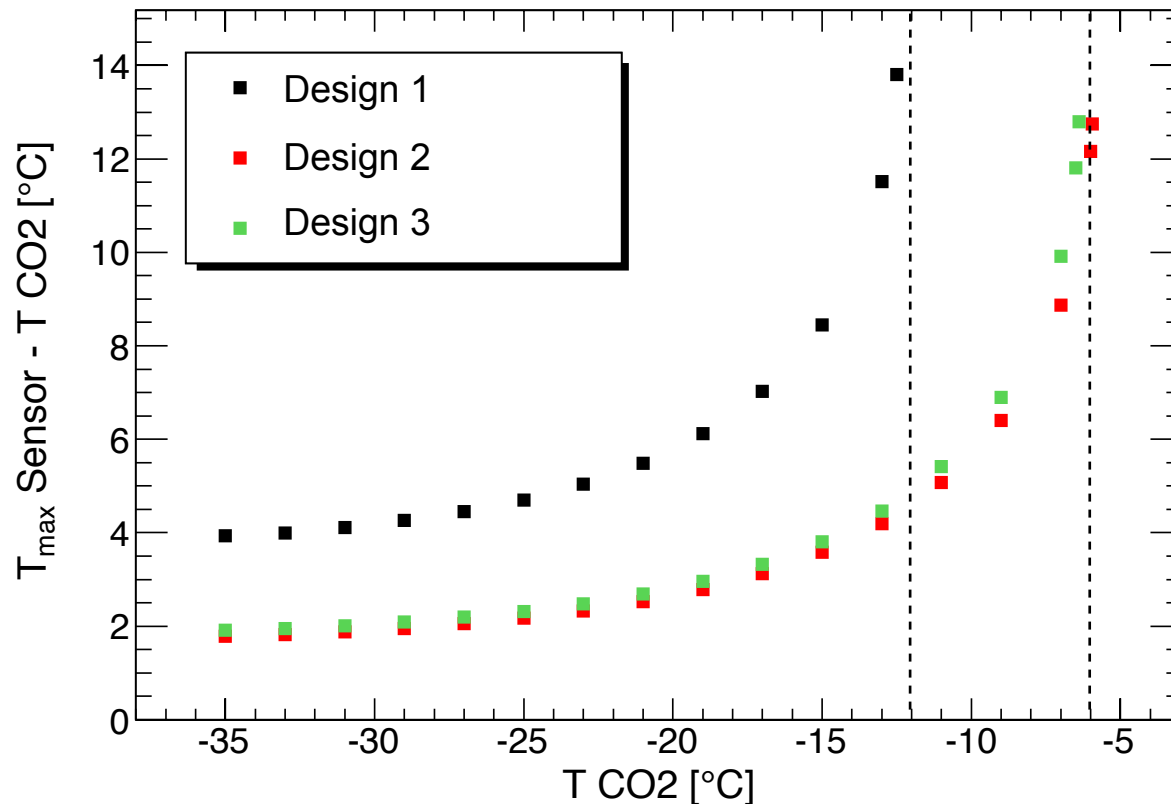
Thermal Finite Element Results - Sensors



- > Temperature of cooling contact tuned to get temperature on sensors below -20°C
- > Very good thermal coupling between sensors and cooling contact
 - temperature gradient between cooling contact and sensor is only 5.2°C (design goal is 10°C)
 - temperature gradient on sensors is 2°C
- > Sensor power consumption is calculated for a uniform temperature distribution
 - power consumption is overestimated $\Rightarrow$ safety margin
- > Study is not sensitive to temperature at which thermal runaway occurs

Thermal Runaway

- > Leakage current doubles for approximately every 7°C increase in temperature
 - positive feedback behavior
 - for too high temperature cooling will not be sufficient
 - module will not be operable → thermal runaway



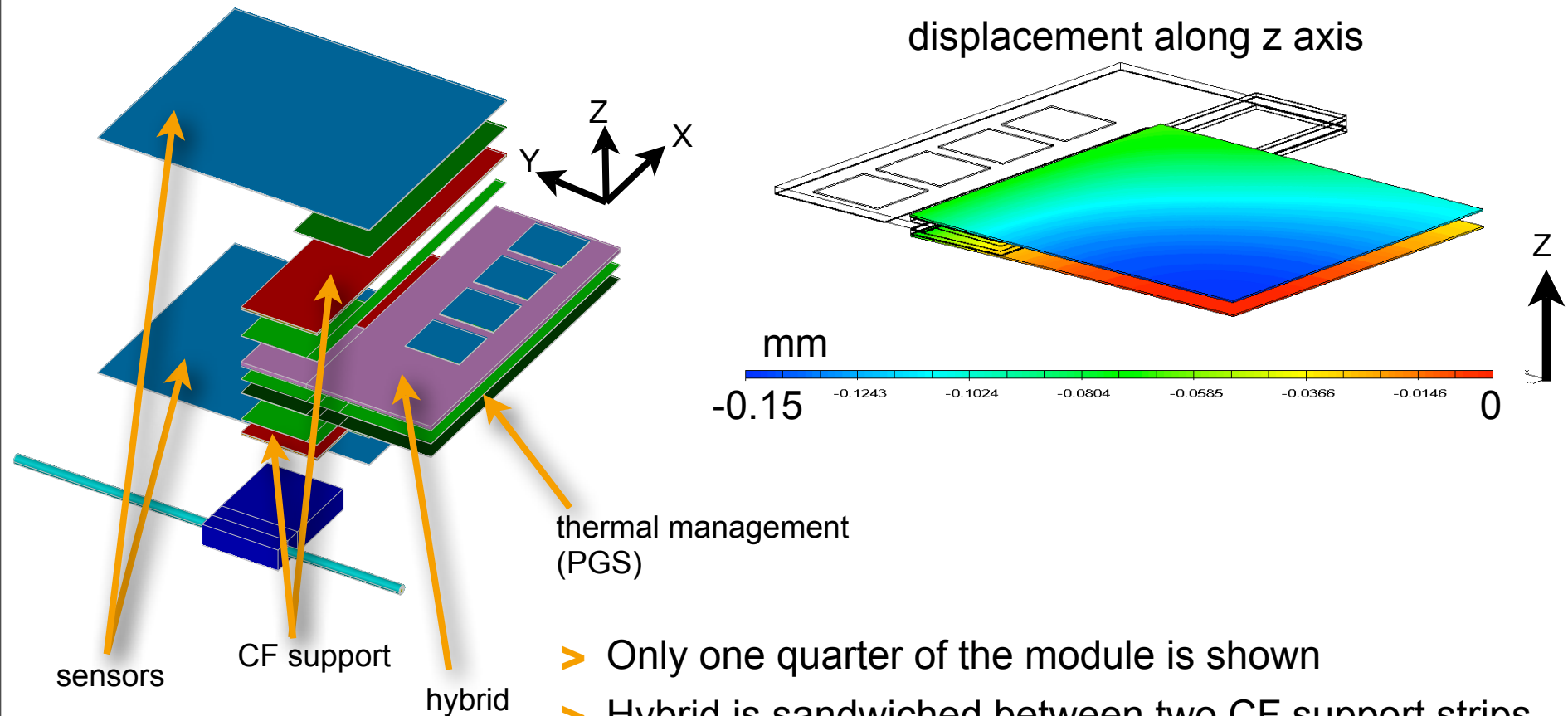
- > Plot shows results from an early design phase
- > Has to be repeated for the 'final' PS and 2S module designs

Thermo-Mechanical Finite Element Analyses

- > All considered module designs consist of multi-layer sandwiches
 - 2S Module: Al/Be heat spreader - CF support - PGS - hybrid substrate
- > Mismatches in the coefficient of thermal expansion (CTE) cause thermal stress and deformation
 - lifetime of sensor can decrease due to stress
 - stress can cause glueings to fail after several thermal cycles
 - deformation can lead to a non-uniform spacing of both sensors in a pT trigger module
- > FE Model from thermal studies is used to investigate stress and deformations
 - results from the thermal FEA are used in the stress analysis
 - module is assumed stress-free at room temperature
- > Results on the next slide are for an early design stage of the 2S module



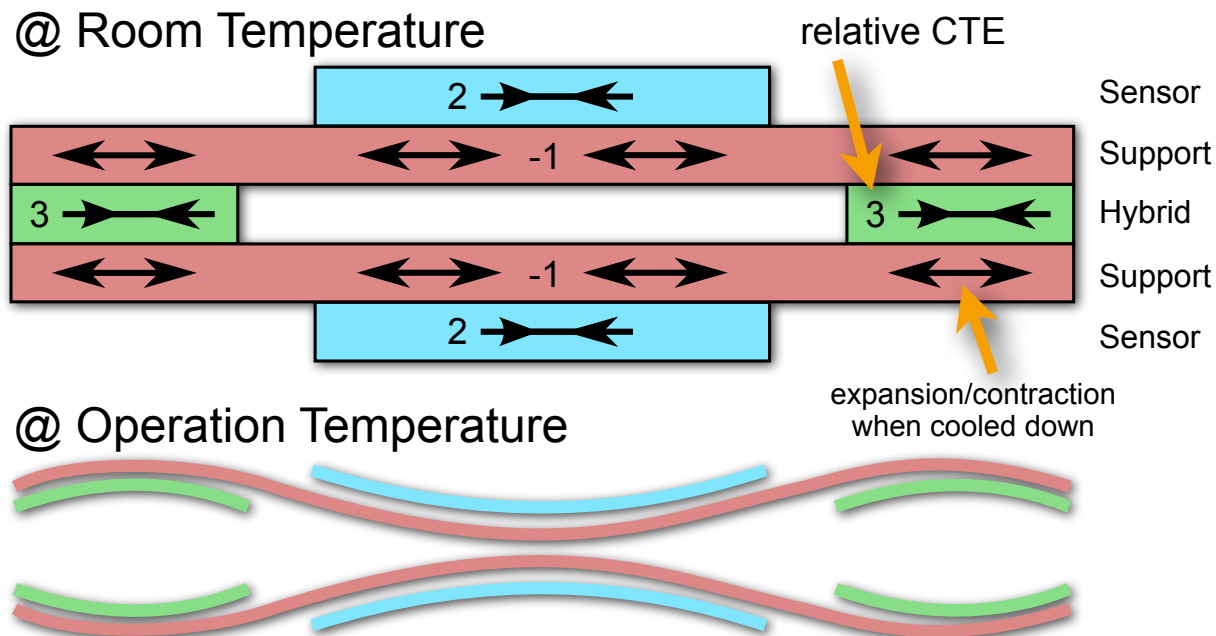
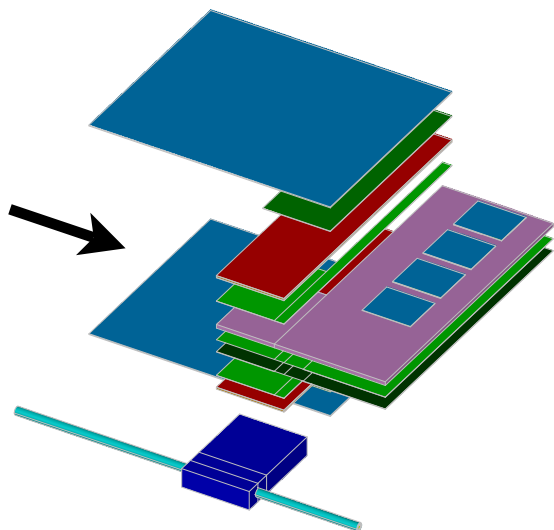
Thermo-Mechanical Results



- > Only one quarter of the module is shown
- > Hybrid is sandwiched between two CF support strips
- > Hybrid is L-shaped

- > Distance between sensors decreases by $150\text{ }\mu\text{m}$ $\rightarrow$ 15% for 1 mm spacing
 - strongly affects the trigger performance

Thermo-Mechanical Results (cont.)



- > Edge: bending due to hybrid vs. CF support CTE mismatch
- > Center: bending due to CF support vs. sensor CTE mismatch
- > Large deformation can be avoided by filling the gap between the support strips
 - too much material reduction can ,amplify' the effects of CTE mismatches

Thermo-Mechanical Results (cont.)

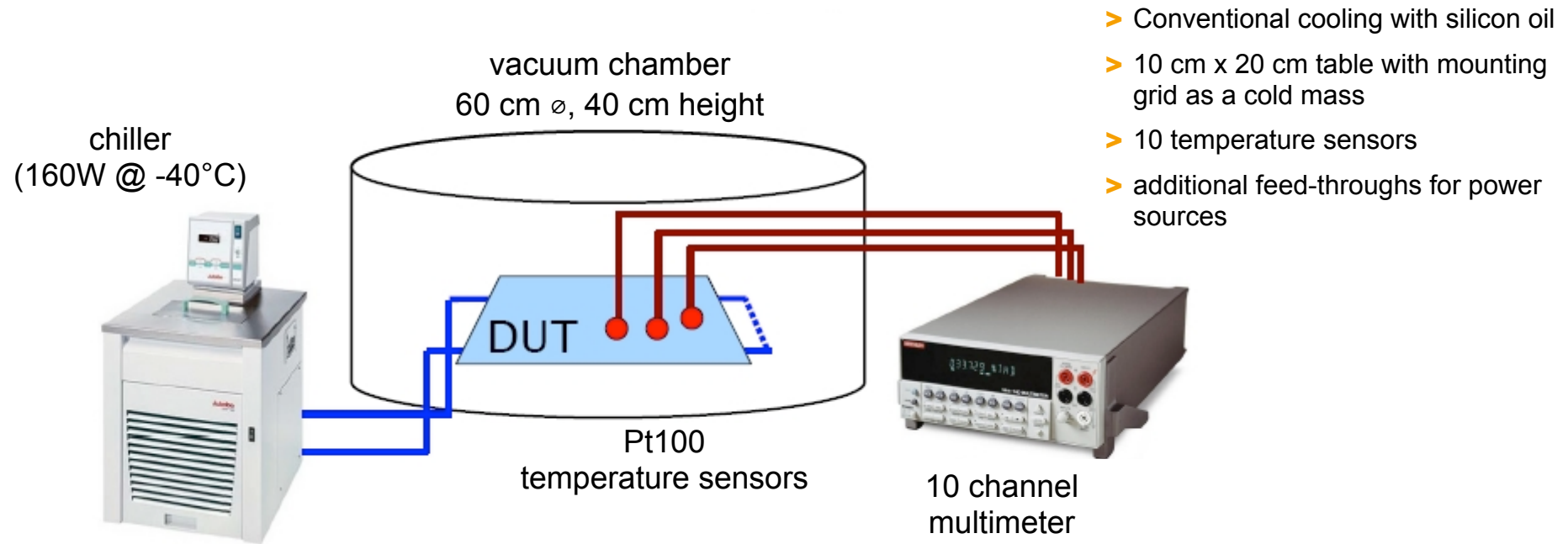
@ Room Temperature

relative CTE

Sensor
support
brid
support
nsor

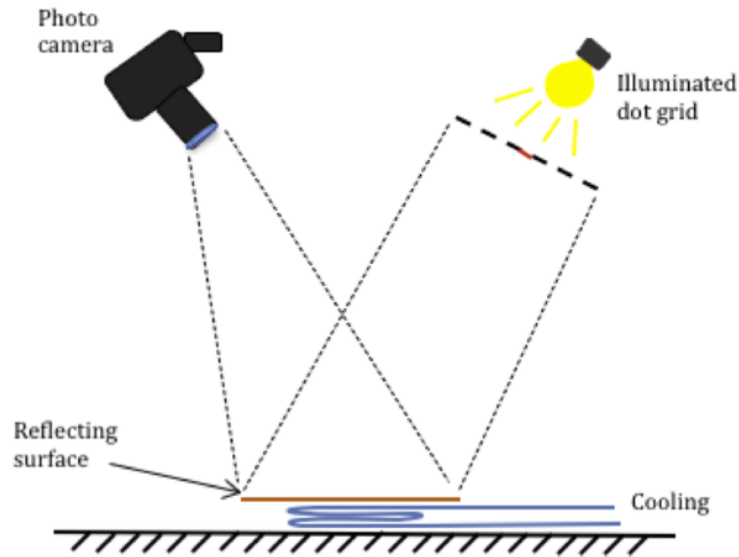
- > Finite element analyses are a powerful tool
 - fast feedback of the behavior and performance of a design
 - allow for a qualitative comparison between design options
- > Finite element models are often too perfect
 - e.g. perfect glue layers with uniform thickness and no air entrapments
 - making the model more realistic is a big effort
- > Results rely on the material properties used in the calculation
 - often not very well known
- > Behavior and performance of design has to be confirmed by measurements
- > Large deformation can be avoided by filling the gap between the support strips
 - too much material reduction can ,amplify' the effects of CTE mismatches

Thermal Measurements

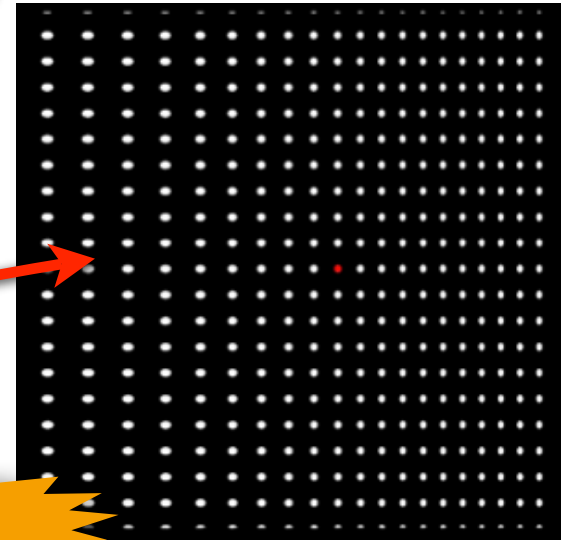
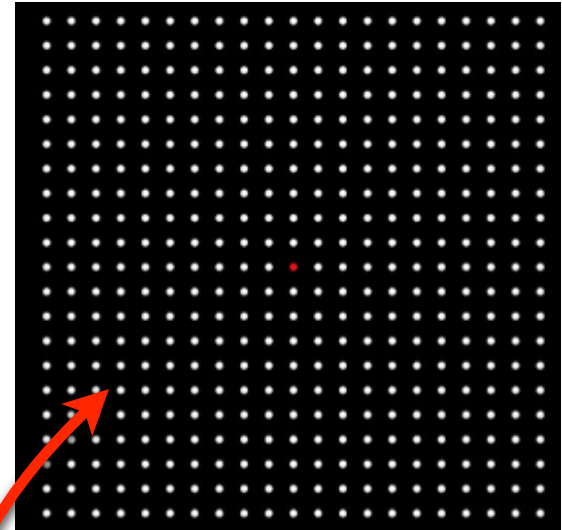


- > Study details of the module design with test structures
 - confirm thermal properties of novel material
 - many aspects of the module designs factorize
 - investigate behavior of gluings and thermal interfaces - e.g. pipe to module
 - feed results back into FEA and module design
- > Measure thermal performance of prototype modules

Optical Deformation Measurements



- > Camera takes pictures of a back-lighted dot-grid through the reflective surface of the DUT
- > Deformation is reconstructed from two images
 - Mirror image off the undeformed surface
 - Mirror image off the deformed surface
- > Based on idea by MPI Munich
- > Initial tests and final design based on raytracer images



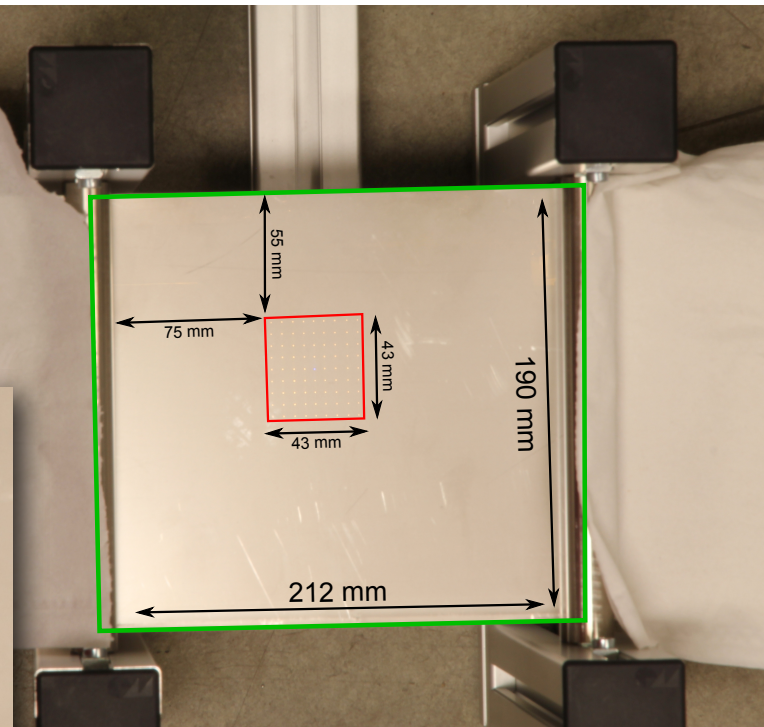
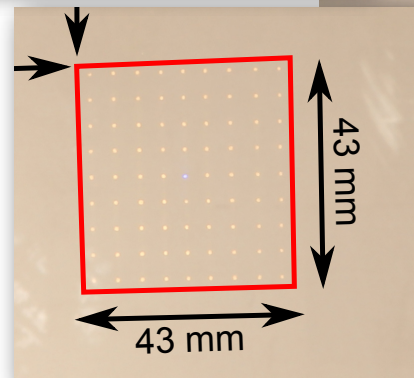
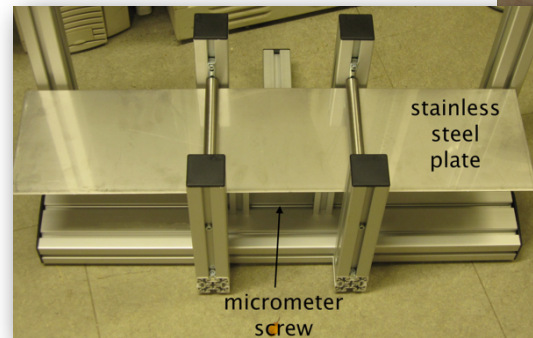
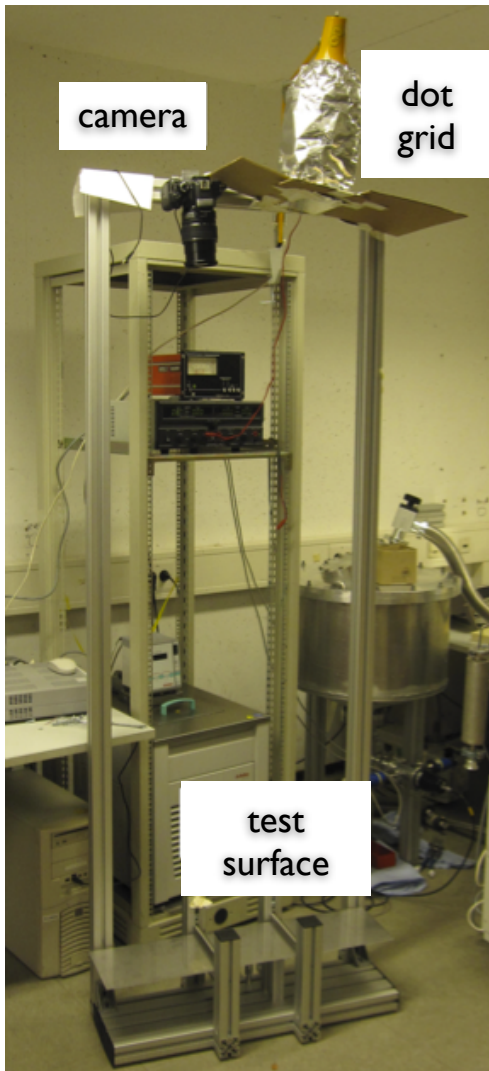
Software by
J. Olzem (DESY)



Test Measurements

- First test measurements have been performed the DESY summer student programm
- Test surface is a polished steel sheet
- Deformed by a precision micrometer screw
- Test measurements suggest a precision of $< 5\mu\text{m}$

S. deRijk



Final Design of the Optical Deformation Setup

- > Final setup will be able to measure components up to 60 cm x 75 cm in size
 - Illuminated dot grid has to be twice the length and width
 - Total size is 250 cm x 150 cm
 - 5 mm x 5 mm in-plane resolution
- > In collaboration with the DESY ATLAS group
 - characterize petals for the ATLAS Silicon Strip Upgrade
- > DUTs have to be cooled to their final operation temperature
 - Time between reference image and deformed image may be several hours
- > Setup itself must not deform within one measurement
 - DUTs will be placed on a granite table
 - Granite table is embedded in aluminium support structure
- > Setup will be flushed with dry air to avoid condensation
- > Camera and dot grid will be movable to adjust to size of DUT and reach best precision



Summary and Outlook

- > For the HL-LHC era CMS will install an improved tracker
 - higher granularity
 - less material
 - trigger capability

- > R&D for the mechanics of the future modules up to now based on FEA
 - Studies have lead to several improvements in the design
 - We are close to a balanced design for the 2S module
thermal vs. thermo-mechanical vs. material budget performance

- > Near-term focus is on the 2S module
 - A detailed list of work packages exists
 - Plan to build a mechanical prototype by the end of this year

- > Measurement setups are in preparation
 - Thermal setup will be available for use by the middle of this year
 - Optical deformation setup will be commissioned by April



