

# Low Level RF for SRF accelerators.

... based on the European XFEL experience

1. Interfaces to LLRF ?
2. LLRF for large scale accelerators

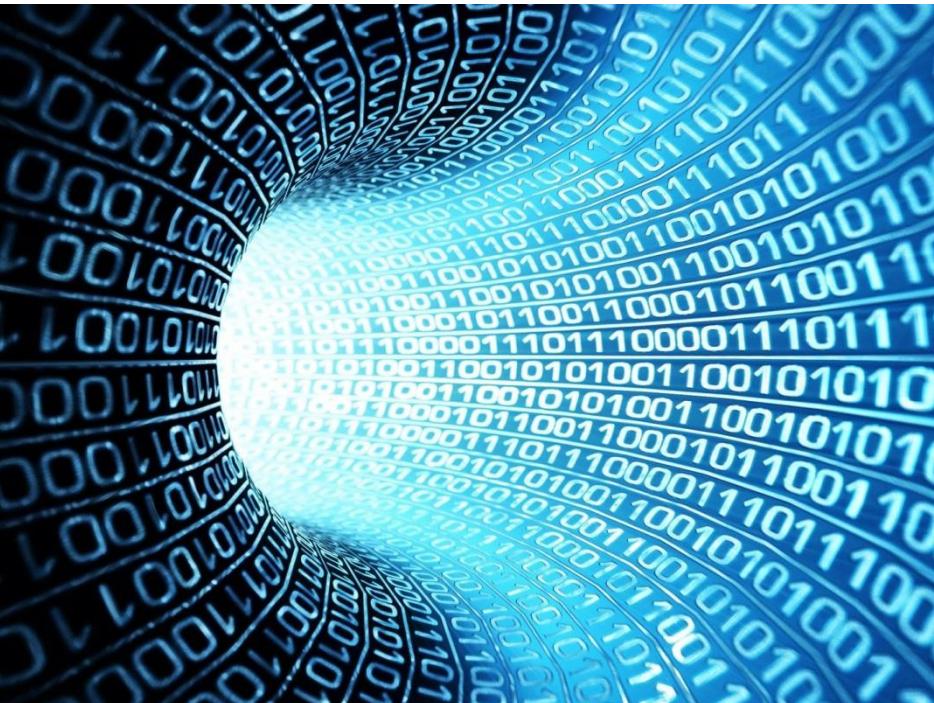
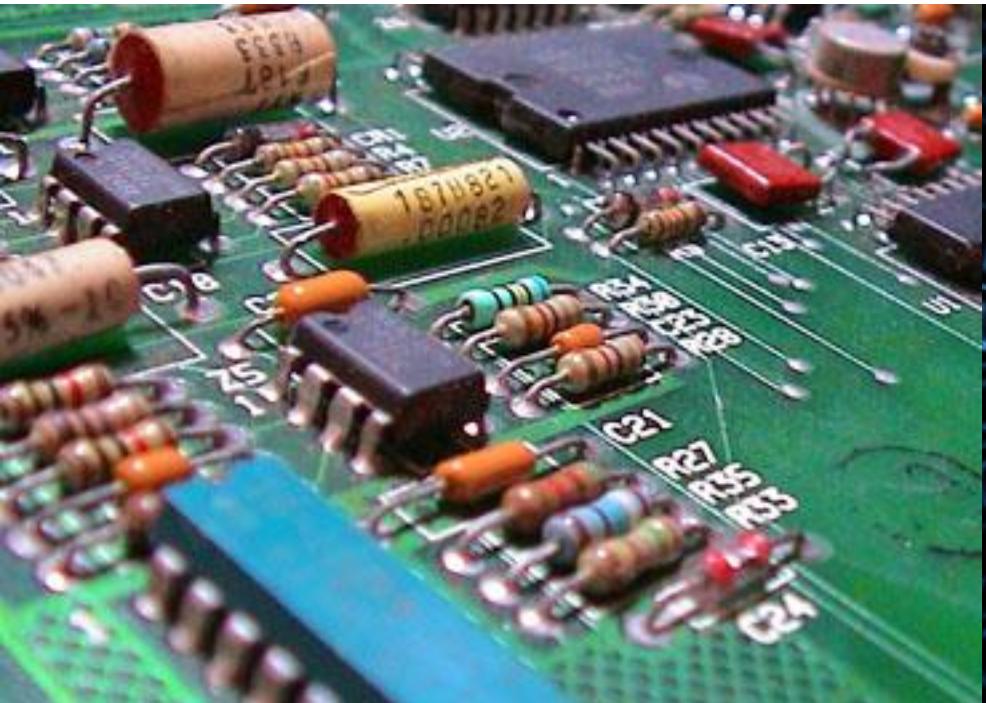
Julien Branlard, DESY  
*for the LLRF team*  
LLRF for SRF accelerators  
Geneva, September 3<sup>rd</sup> 2014

# WHY TALK ABOUT LLRF ?

- “Everything already demonstrated since analog LLRF systems.”

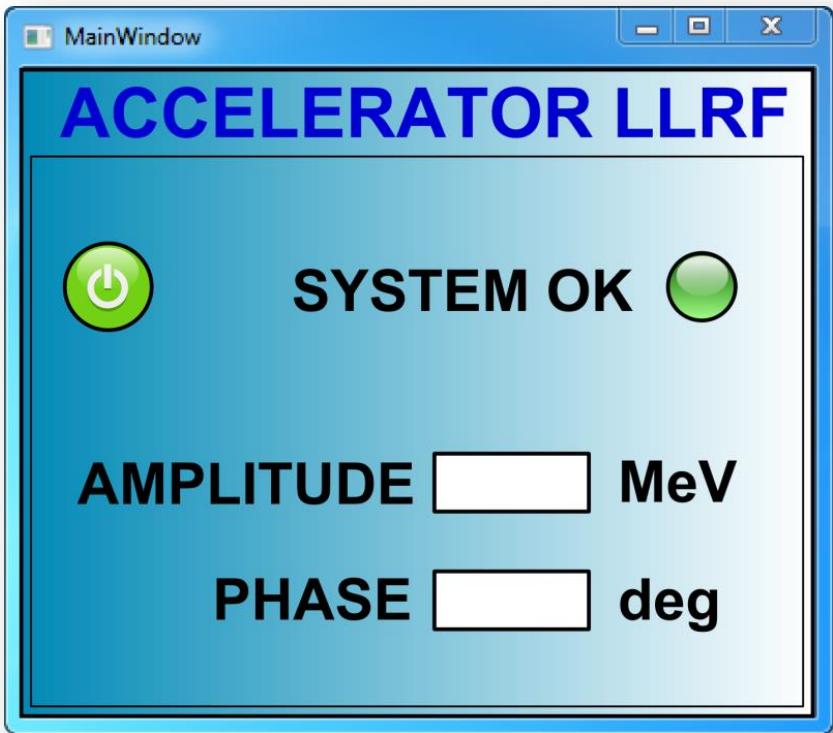
BUT

- “New technologies open new possibilities, offer new challenges.”

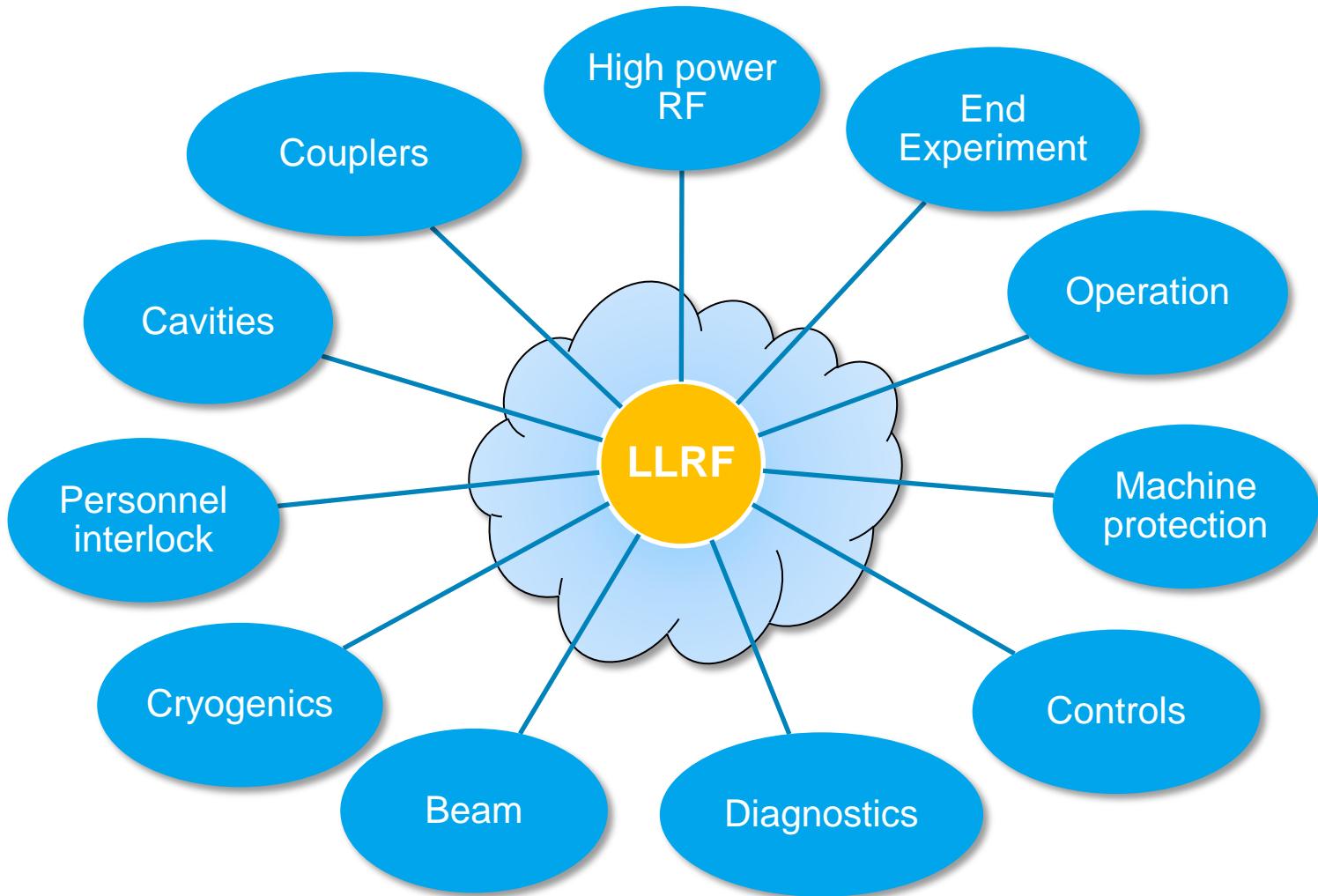


# WHAT IS LLRF ?

- Interface to « The Ultimate LLRF System »



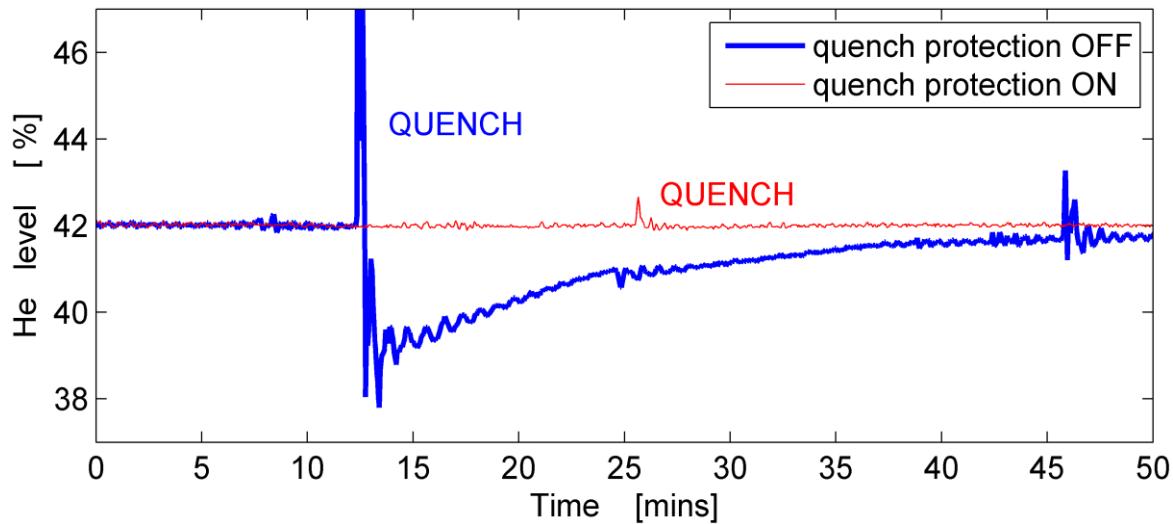
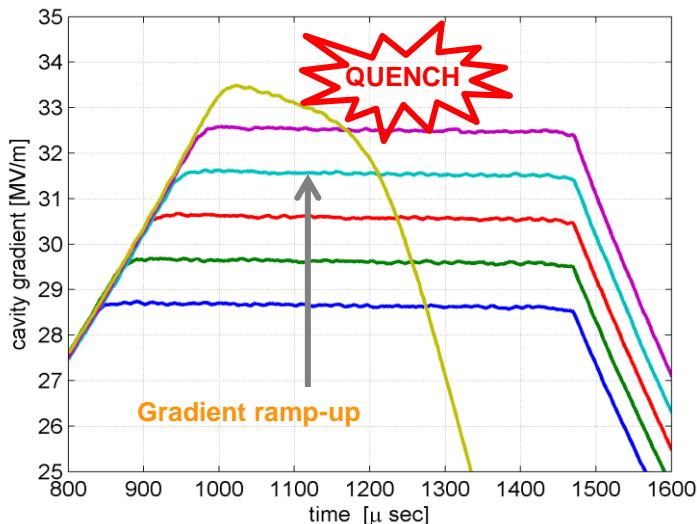
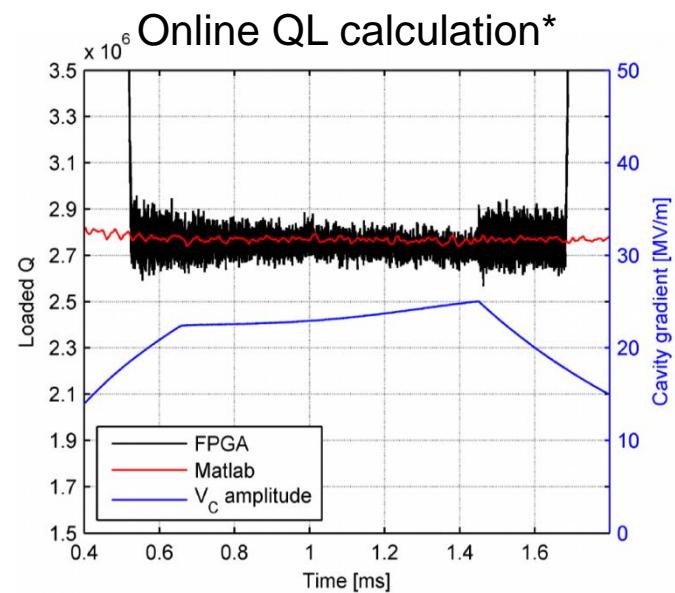
# WHERE DOES LLRF STOP ?



- > INTERFACES TO LLRF
- > LLRF FOR LARGE SCALE ACCELERATORS

# LLRF and Cryogenics

- Quench detection
- Heat load anticipation / compensation
- Cryo OK → tuners, piezo



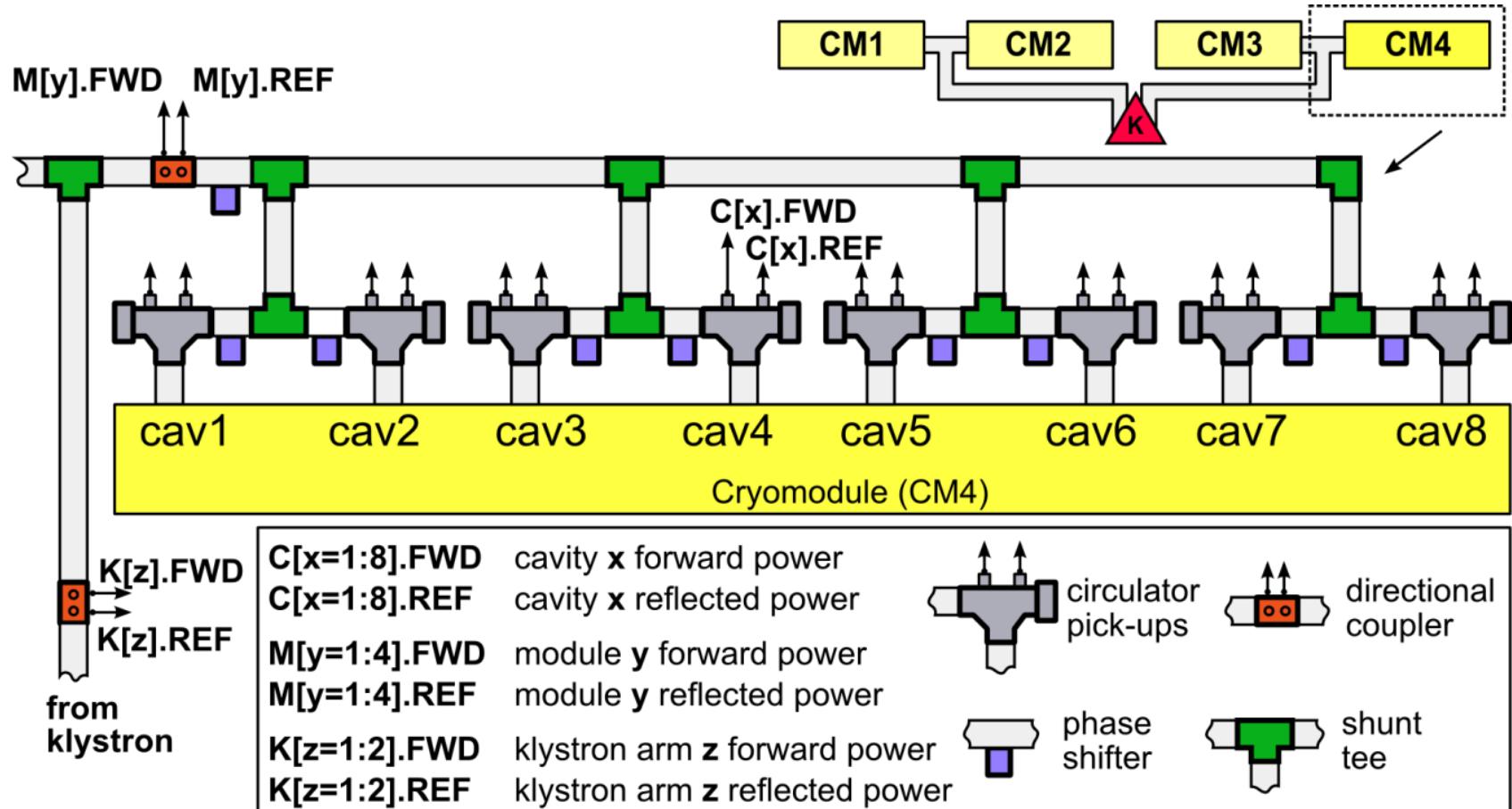
\* Courtesy: R. Rybaniec

"Real-time Estimation of Superconducting Cavities Parameters"

IPAC 2014, Dresden Germany

# LLRF and High Power RF (1/2)

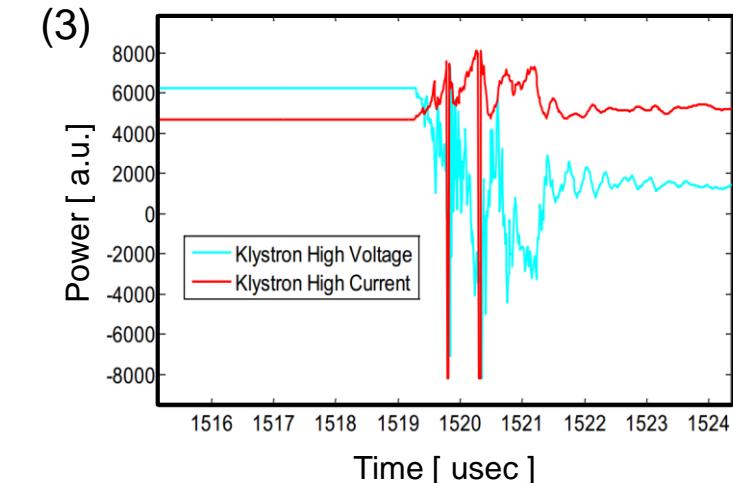
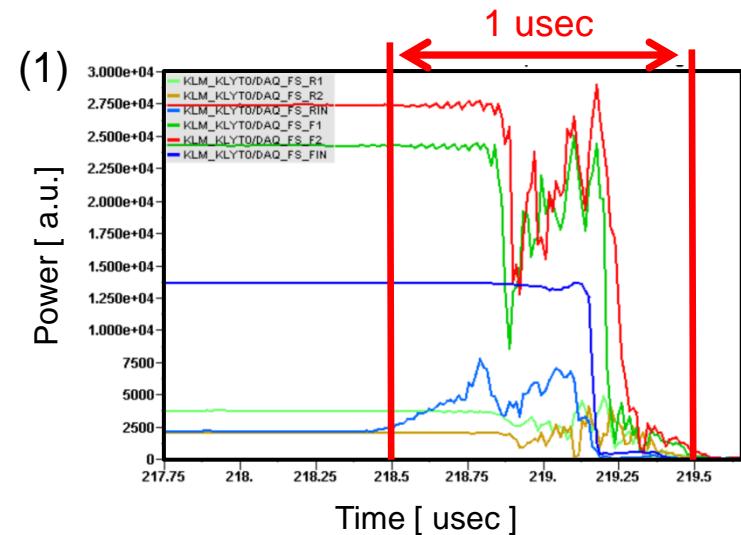
## > Power sub-distribution and phase shifters control



## > Klystron monitoring

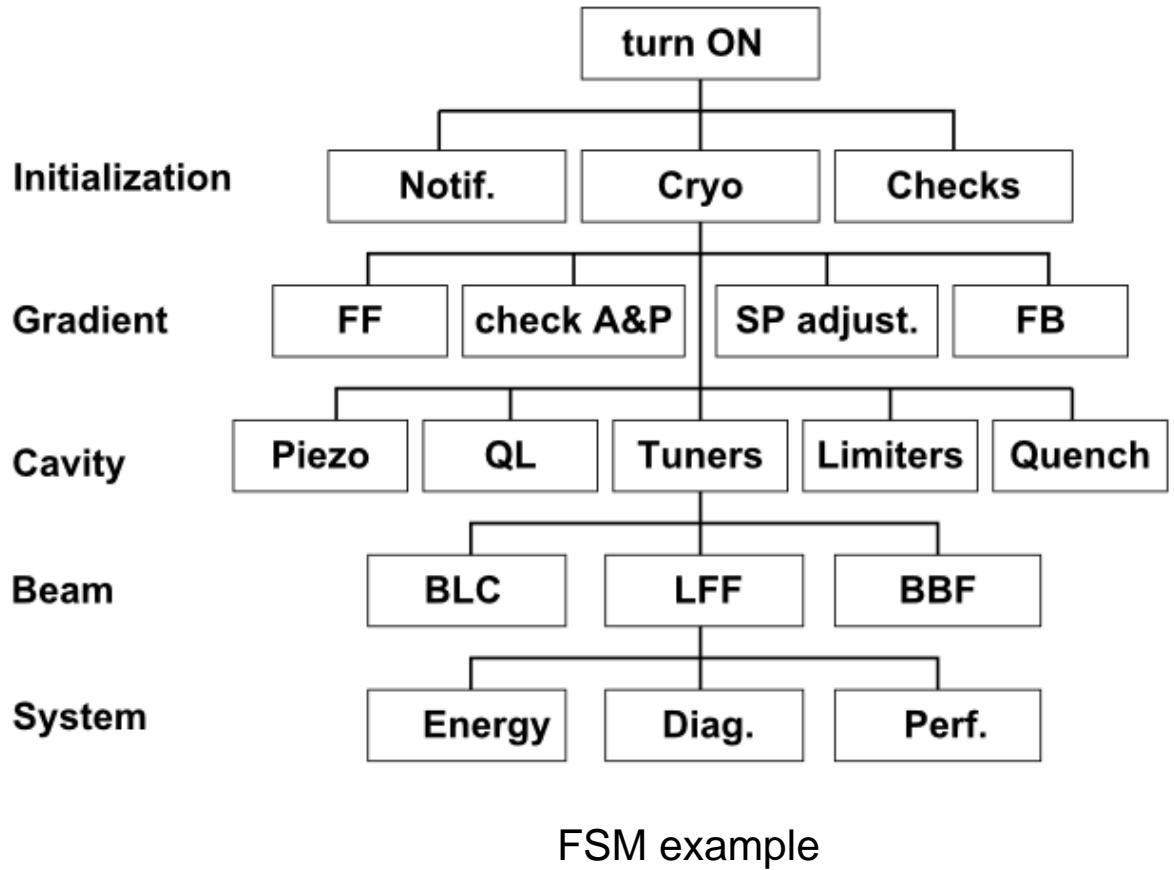
- (1) - RF break-down
- (2) - “Too-high” reflected power
- (3) - High voltage break-down

- Fast interlock of the LRF drive
- 200 nsec reaction time



# LLRF and Operation (1/2)

- RF station ON/OFF
- Finite State Machine
- Exception handling



FSM example

# LLRF and Operation (2/2)

- RF station ON/OFF
- Finite State Machine
- Exception handling
- Operator interface GUI
- Alerts / warning visibility

*Intuitive GUIs*

*Layered complexity*

*Explicit alarms*

*Panel navigation*

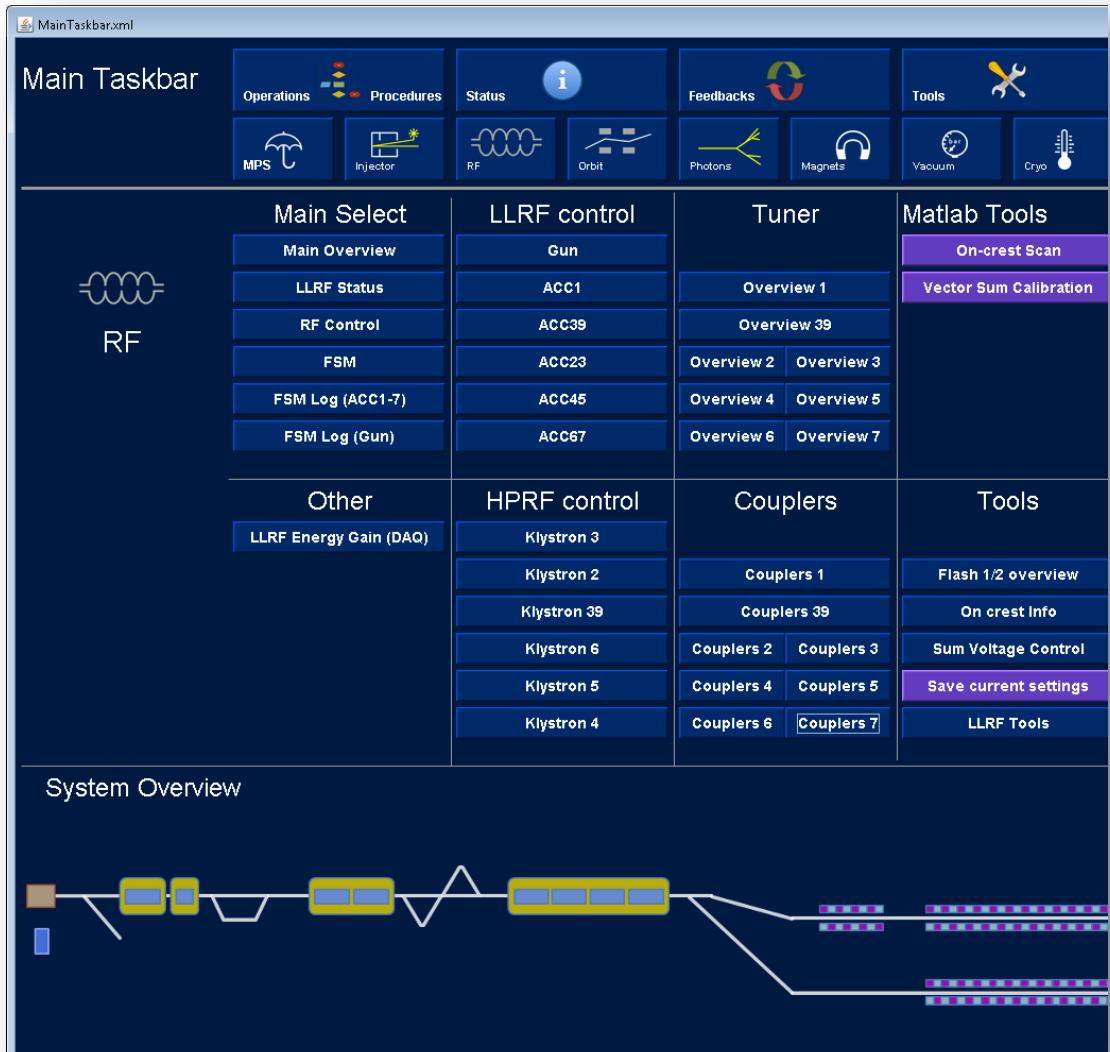
*Complexity abstraction*

*Concentration of relevant data*

*Same data, different representation*

...

- **Automation**



## > Tuner motor

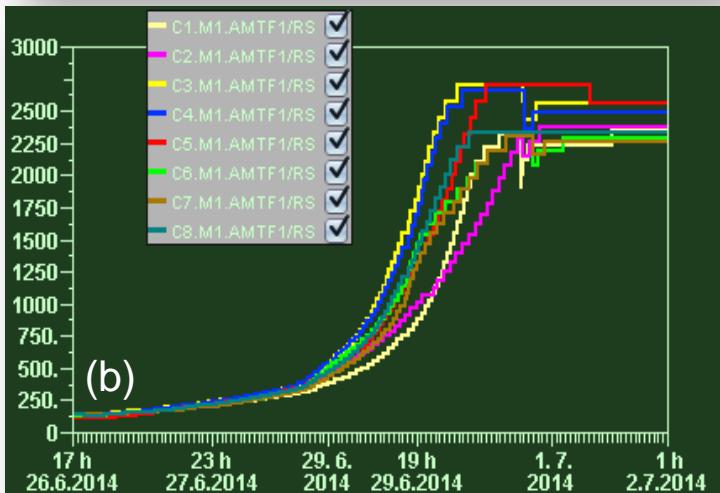
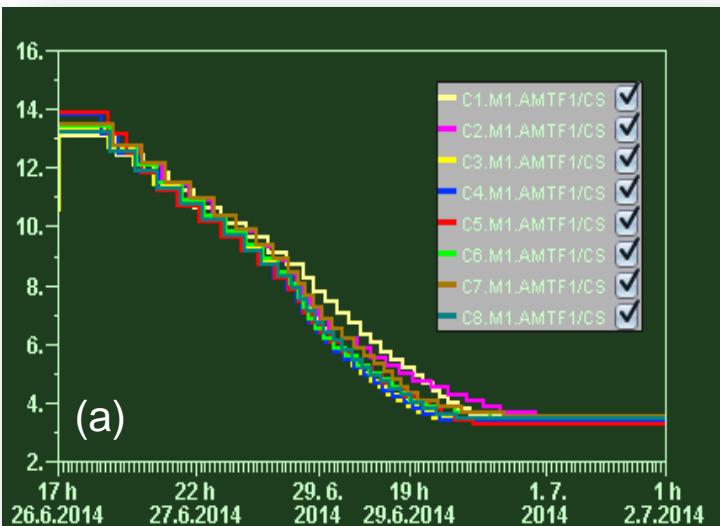
- Tuning
- Detuning
- Cool down / warm up
- Piezo relaxation

## > Piezo

- Microphonics
- LFD compensation
- Cavity fine tuning
- Piezo capacitance measurement

## > Gun

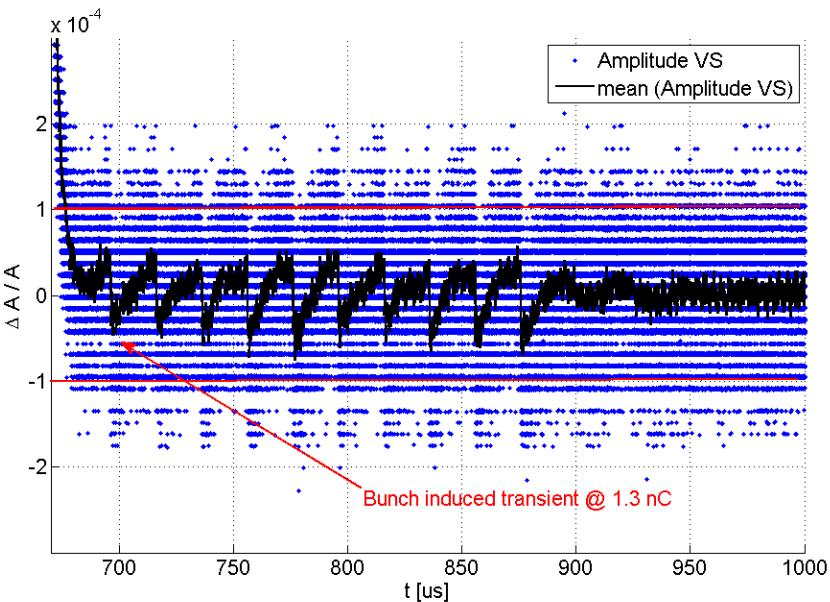
- Cooling (water temperature)
- Flat-top length regulation



Piezo capacitance (a) and resistance (b)  
during cool down

# LLRF and Beam (1/2)

- BAM, BCM → BBF
- Toroid → BLC
- Beam phase
- Beam transients → channel alignment

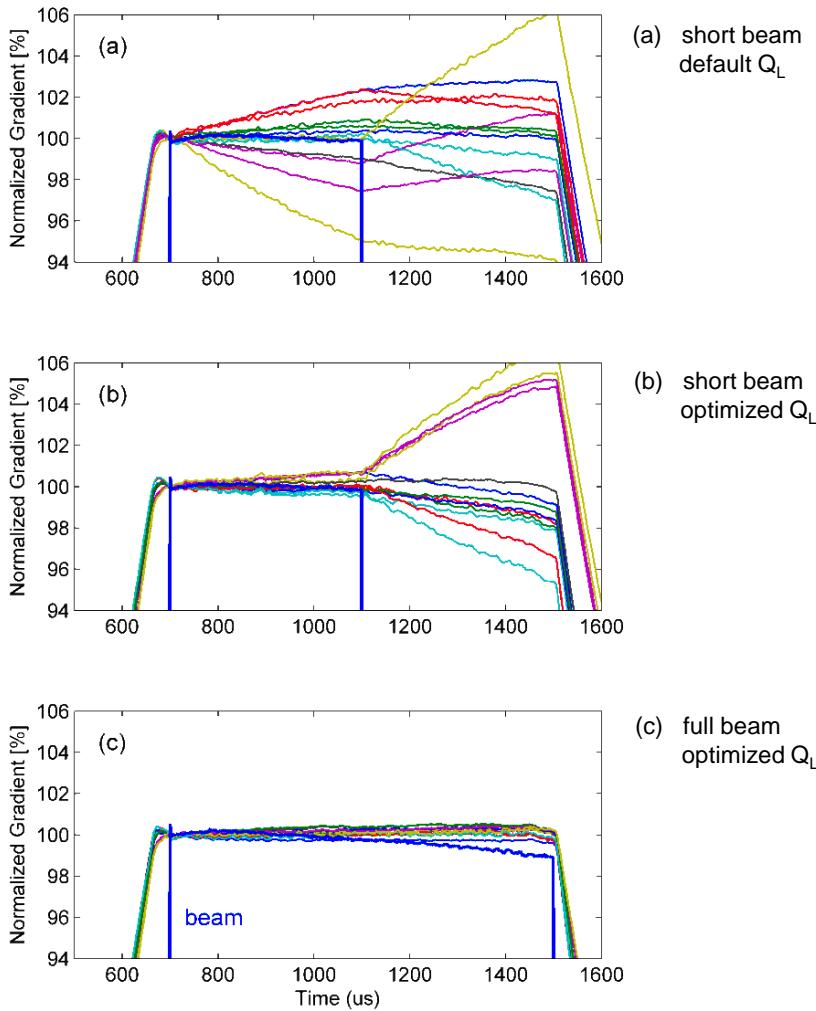


Channel delay alignment using single bunch transients

# LLRF and Beam (2/2)

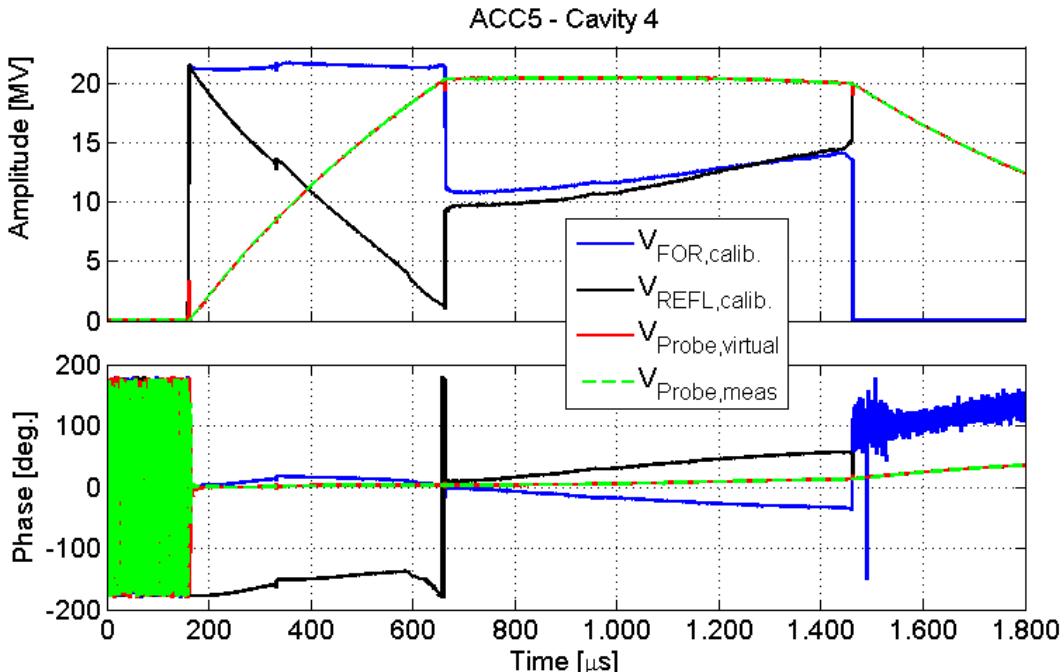
- BAM, BCM → BBF
- Toroid → BLC
- Beam phase
- Beam transients → channel alignment
- Beam profile → TDS, BC
- Beam energy → VS calibration
- Beam loading →  $Q_L$  adjustments
- ...

Reference: J. Branlard *et al.*  
"LLRF Automation for the 9mA ILC Tests at FLASH"  
LINAC 2012, Tel Aviv, Israel



- Beam diagnostics (BPM, BLM, BAM, toroid, etc..)
- LLRF diagnostics

- Performance (intra- inter-train)
- Heat load estimation
- Virtual probe



Virtual probe calculation

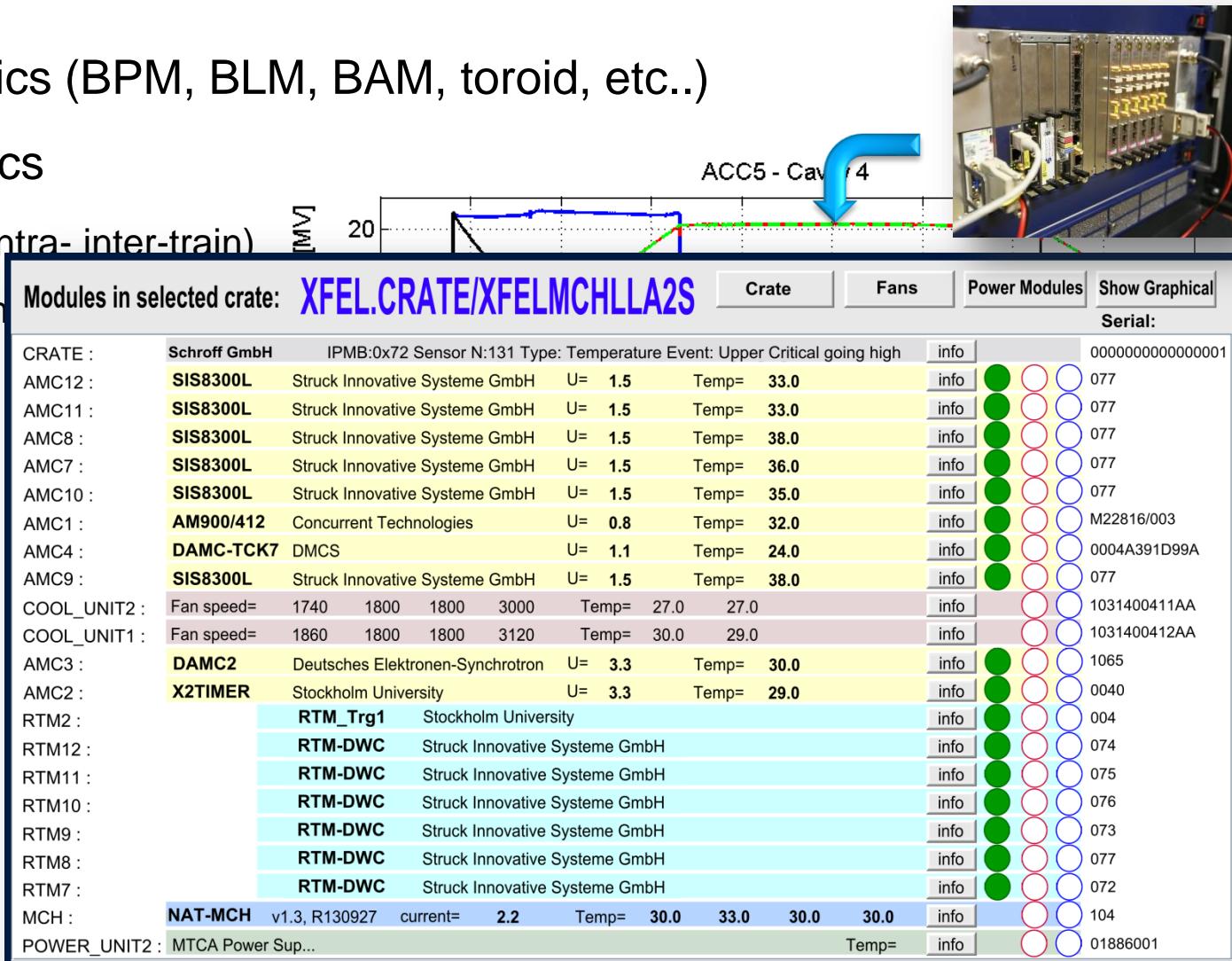
# LLRF and Diagnostics (2/2)

- Beam diagnostics (BPM, BLM, BAM, toroid, etc..)
- LLRF diagnostics

- Performance (intra- inter-train)
- Heat load estimation
- Virtual probe

- HOM
- Radiation
- System health

- Temperature
- Fan speed
- Piezo
- CPU load
- ...



## > Controls

- Real time capabilities
- DAQ
- Front-end (controls)
- Middle layer (Diagnostics)

## > Machine Protection

- Interlocks (MPS)
- Cryo OK ?
- LLRF alarm

## > RF Couplers

- QL control (motor / 3 stub tuners)
- Conditioning
- Interlocks (e-, light)
- Heating

## > Personnel Protection

- Personnel interlock
- RF permit

## > Experiments

- RF Reference distribution
- Beam stability (BAM, energy)

## > ...

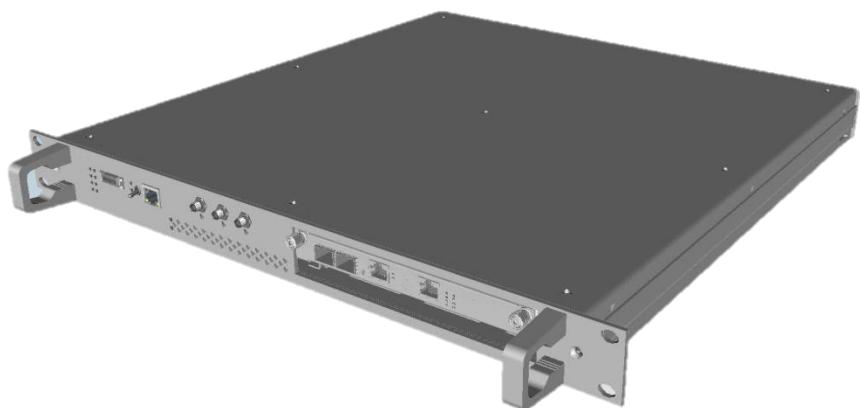


- INTERFACES TO LLRF
- LLRF FOR LARGE SCALE ACCELERATORS

# LLRF FOR LARGE SCALE ACCELERATORS

## > Mass production

- Specifications
- Call for tender
- Documentation
- 3D models
- Test procedure with firmware
- Non-conformity report
- Etc...



Deutsches Elektronen-Synchrotron Ein Forschungszentrum der Helmholtz-Gemeinschaft		European XFEL										
Titel/Title	Specification Document for the TMC-Board: <b>TMCB</b> (Temperature Monitoring & Control Board) 2.0 *** Draft Version ***	Projekt/Project FLASH-WP02-XTCA										
Autor/Author	Marie Czwalima (MC)	Dokument-Nr./Document identifier Board Revision Number 2.0										
Mitautor(en)/Co-Author(s)	Jaroslaw Szewinski (JS), Jan Piekarzki (jP), Frank Ludwig (FL), Michael Fenner (MF), Borut Repš (BR), Gašper Jug (GJ)											
<p>This document describes the requirements for the system subcomponent: Temperature Monitoring and Control Board. The module is a packaged prototype for the XFEL.</p> <p><b>Subcomponent : TMC-Board for all LLRF and synchronisation system 19" modules</b></p> <table border="0"> <tr> <td>- Drift Calibration Module (DCM)</td> <td>approx. 50 pcs</td> </tr> <tr> <td>- Local Axis Monitor (LAM)</td> <td>approx. 100 pcs</td> </tr> <tr> <td>- Laser-to-RF set-up (L2RF)</td> <td>approx. 15 pcs</td> </tr> <tr> <td>- Local Oscillator Generation Module (LOGM)</td> <td>approx. 10 pcs</td> </tr> <tr> <td>- Transverse Deflecting Structure (TDS)</td> <td>approx. 10 pcs</td> </tr> </table>			- Drift Calibration Module (DCM)	approx. 50 pcs	- Local Axis Monitor (LAM)	approx. 100 pcs	- Laser-to-RF set-up (L2RF)	approx. 15 pcs	- Local Oscillator Generation Module (LOGM)	approx. 10 pcs	- Transverse Deflecting Structure (TDS)	approx. 10 pcs
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- Transverse Deflecting Structure (TDS)	approx. 10 pcs											
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\* (Updated version will follow.)

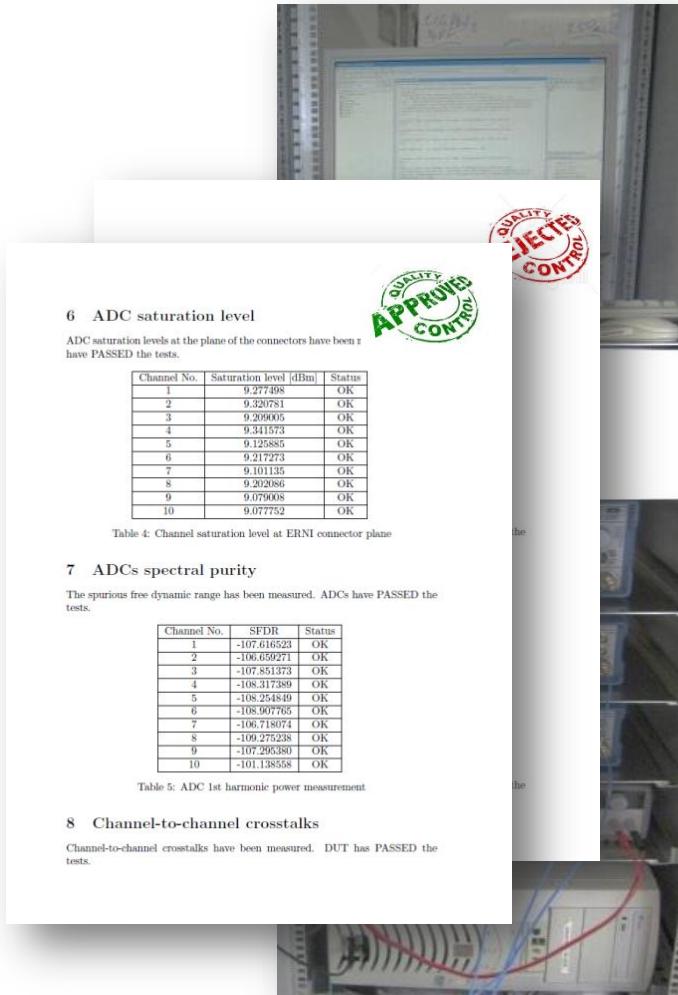
- 1 / 27



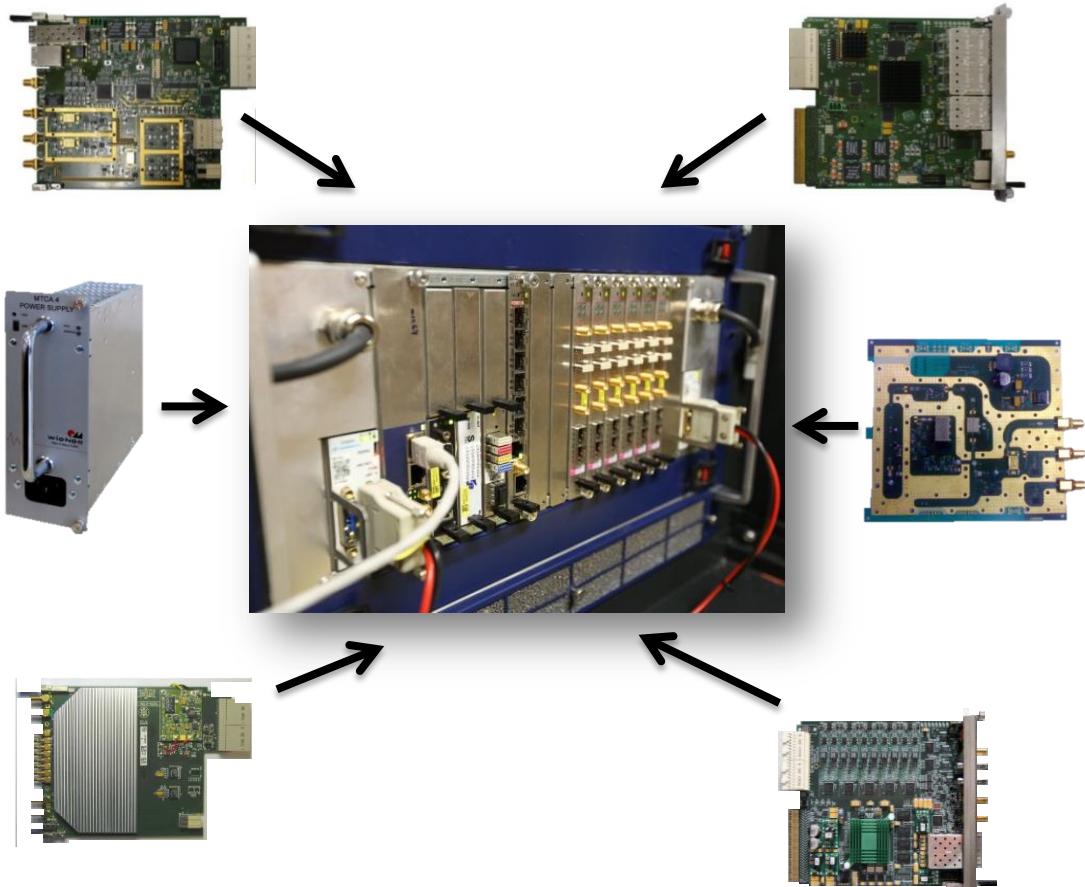
# LLRF FOR LARGE SCALE ACCELERATORS

## > Quality Control

### Test Stands



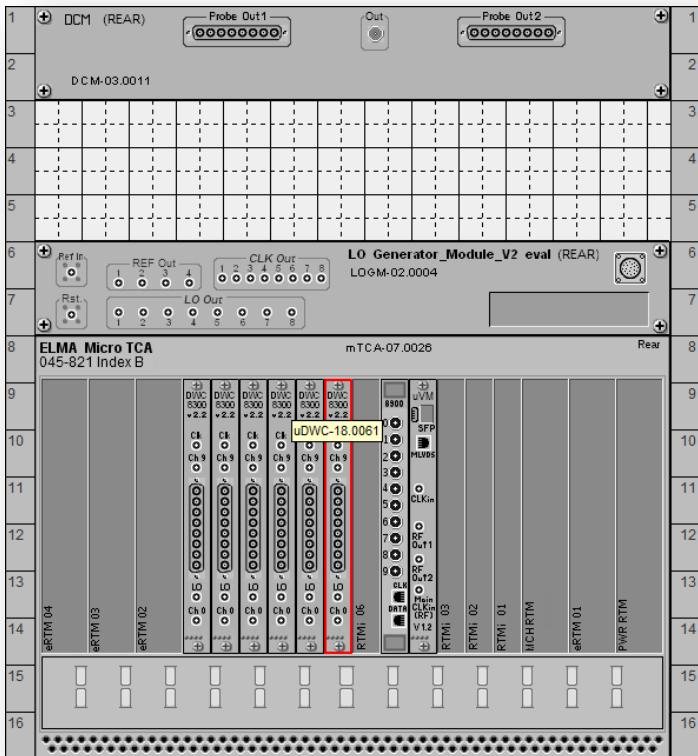
### System Integration



# LLRF FOR LARGE SCALE ACCELERATORS

## > Installation

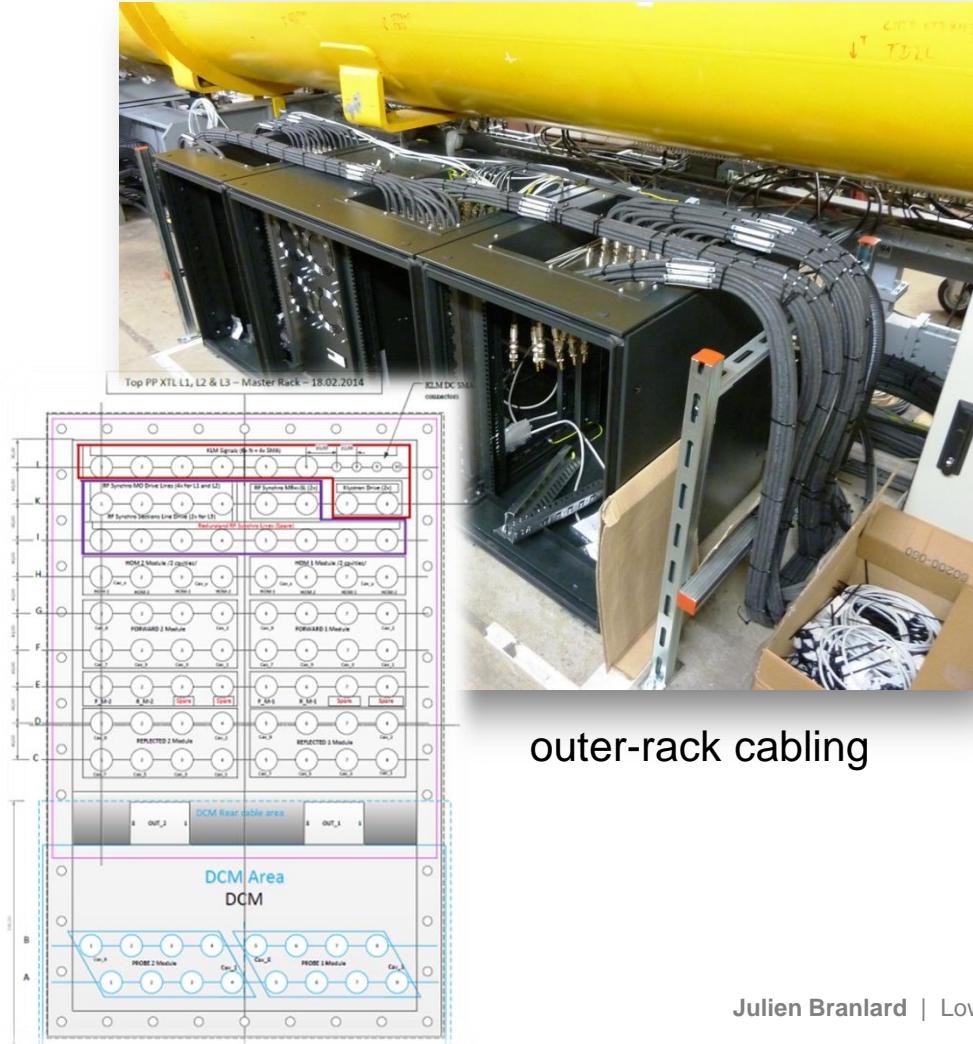
- Procedure
- Check list
- Labelling
- Device tracking



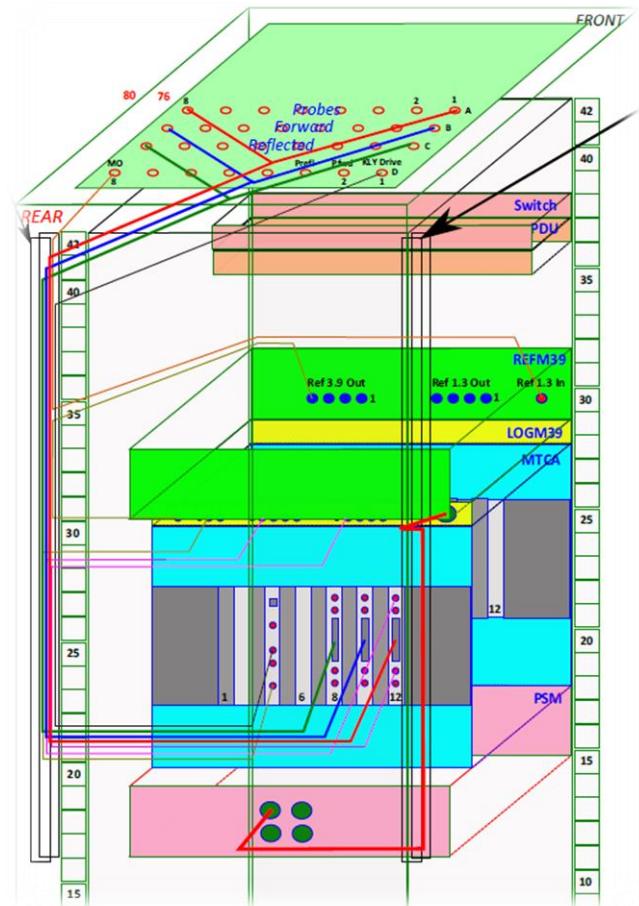
WP02 - LLRF							
 <b>Deutsches Elektronen-Synchrotron</b> Ein Forschungszentrum der Helmholtz-Gemeinschaft							
Title: WP02 LLRF							
MTCA crate installation check list							
Destination	<input type="checkbox"/> INJ	<input type="checkbox"/> L1	<input type="checkbox"/> L2	<input type="checkbox"/> L3	RF station #	<input type="checkbox"/> MASTER	<input type="checkbox"/> SLAVE
CPU name:							
MCH name:							
Shipment do	KDS number	Model					
Labelling do	MTCA crate	<input type="checkbox"/> ELMA		<input type="checkbox"/> SCHROFF		<input type="checkbox"/> RFB	
KDS entry do		Version	RTM	KDS #	Version		
Factory test:	-1 <input type="checkbox"/> uPM						
Factory test:	0 MCH						
Unit:	1 CPU						
Resu	2 TMG						
Failure:	3						
Ready-for-te	4 uTC						
Incoming ins	5						
	6						
	7 uADC						
	8 uADC						
	9 uADC						
	10 uADC						
	11 uADC						
	12 uADC						
	13 uPM						
	14						
	15						
	16						
Notes:							
XFEL LLRF system installation procedure.docx							

# LLRF FOR LARGE SCALE ACCELERATORS

## > Large channel integration



outer-rack cabling

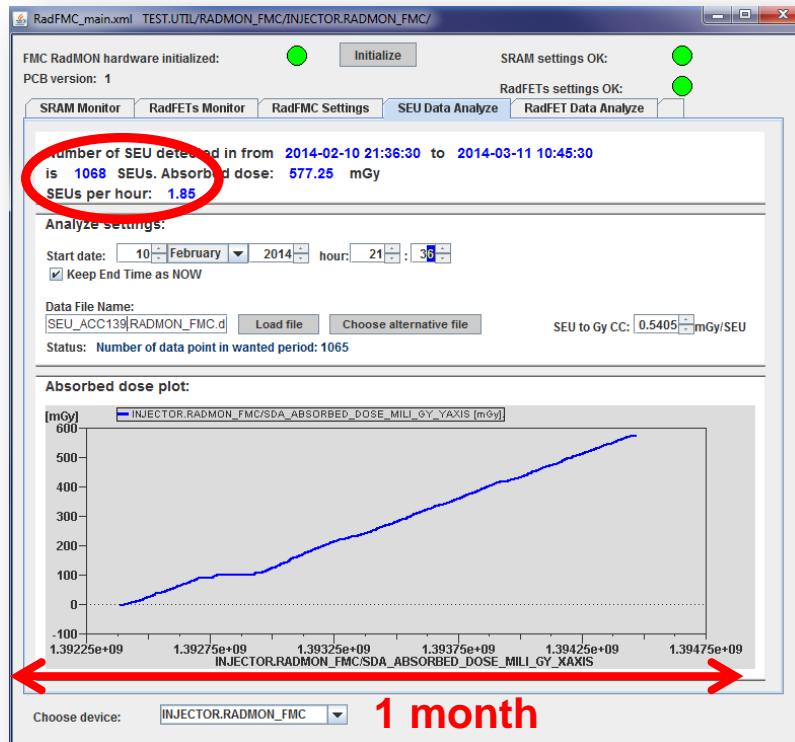


inner-rack cabling

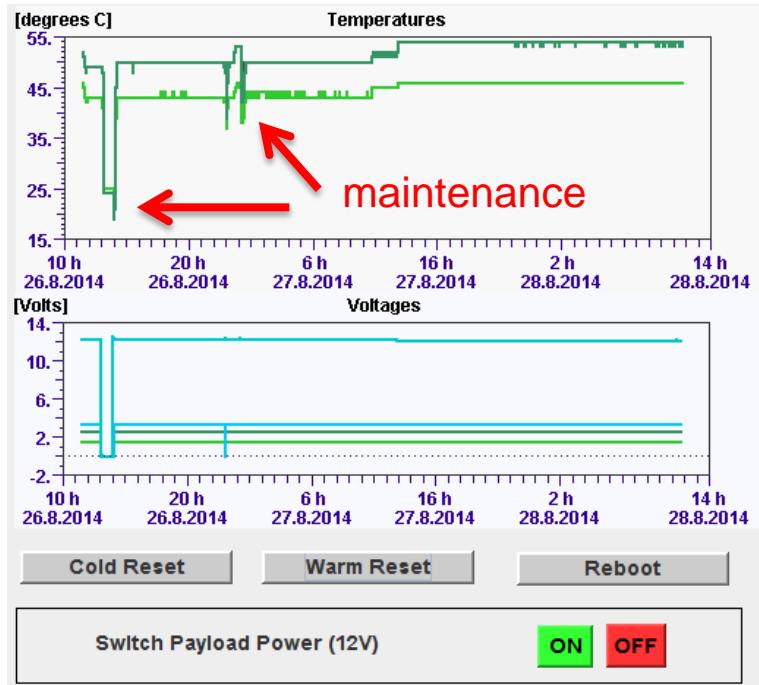
# LLRF FOR LARGE SCALE ACCELERATORS

## > Remote “everything”

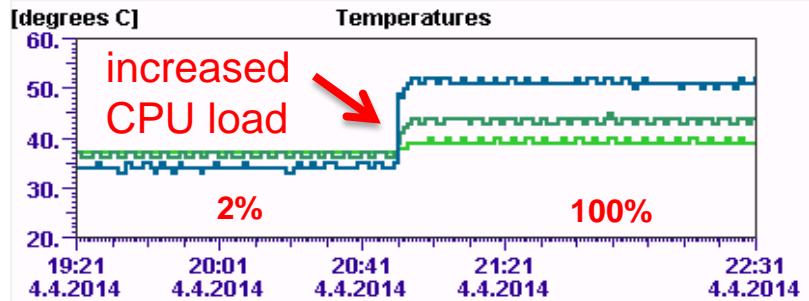
- System health monitoring
- System upgrades (FW / SW)
- Management (on / off / swap)



Radiation monitoring in tunnel



Temperature monitoring

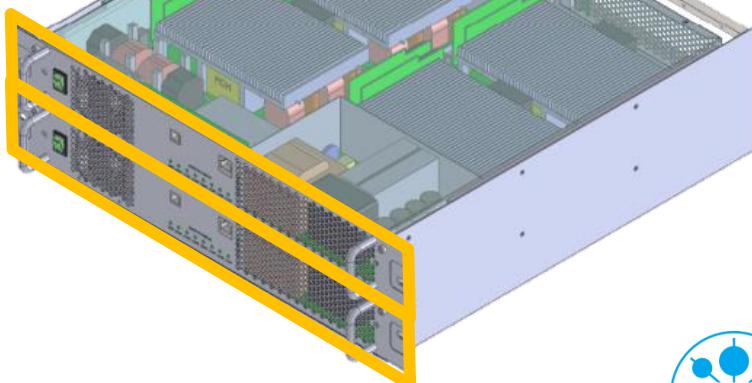
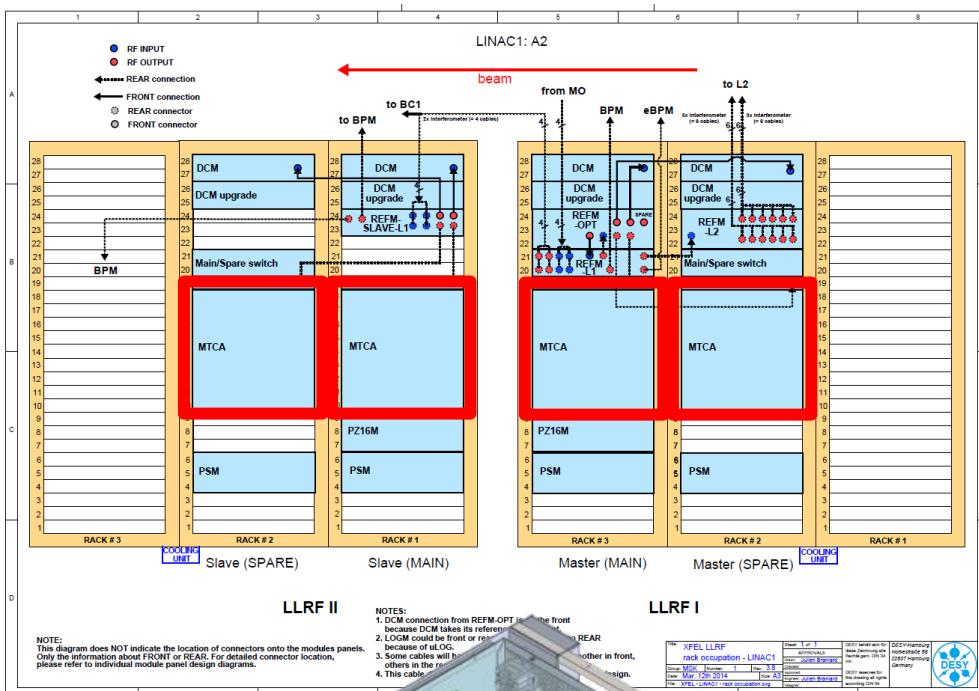


# LLRF FOR LARGE SCALE ACCELERATORS

## > Remote “everything”

- System health monitoring
- System upgrades (FW / SW)
- Management (on / off / swap)

## > Redundancy



## > Automation

- For operation
- For machine protection

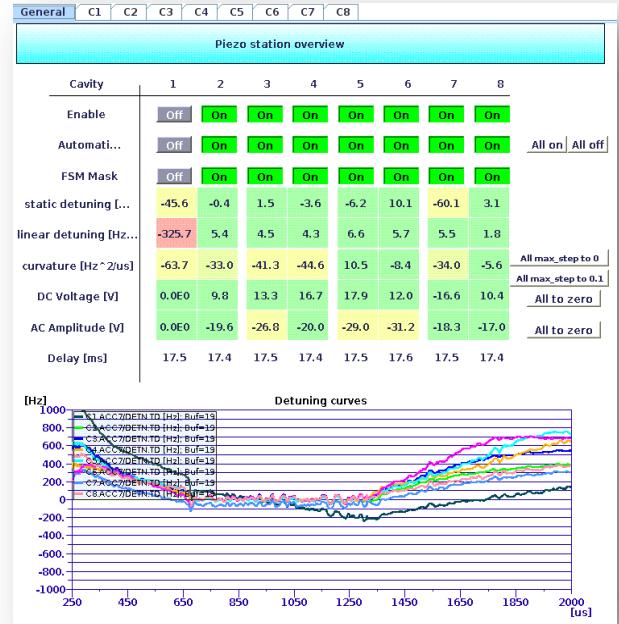
*Frequency tuning / detuning  
Bandwidth control  
Diagnostics  
Quench  
Startup/shutdown  
Calibration  
Performance  
...*

**Exception Handling  
Automation Priorities**

### Cavity bandwidth control

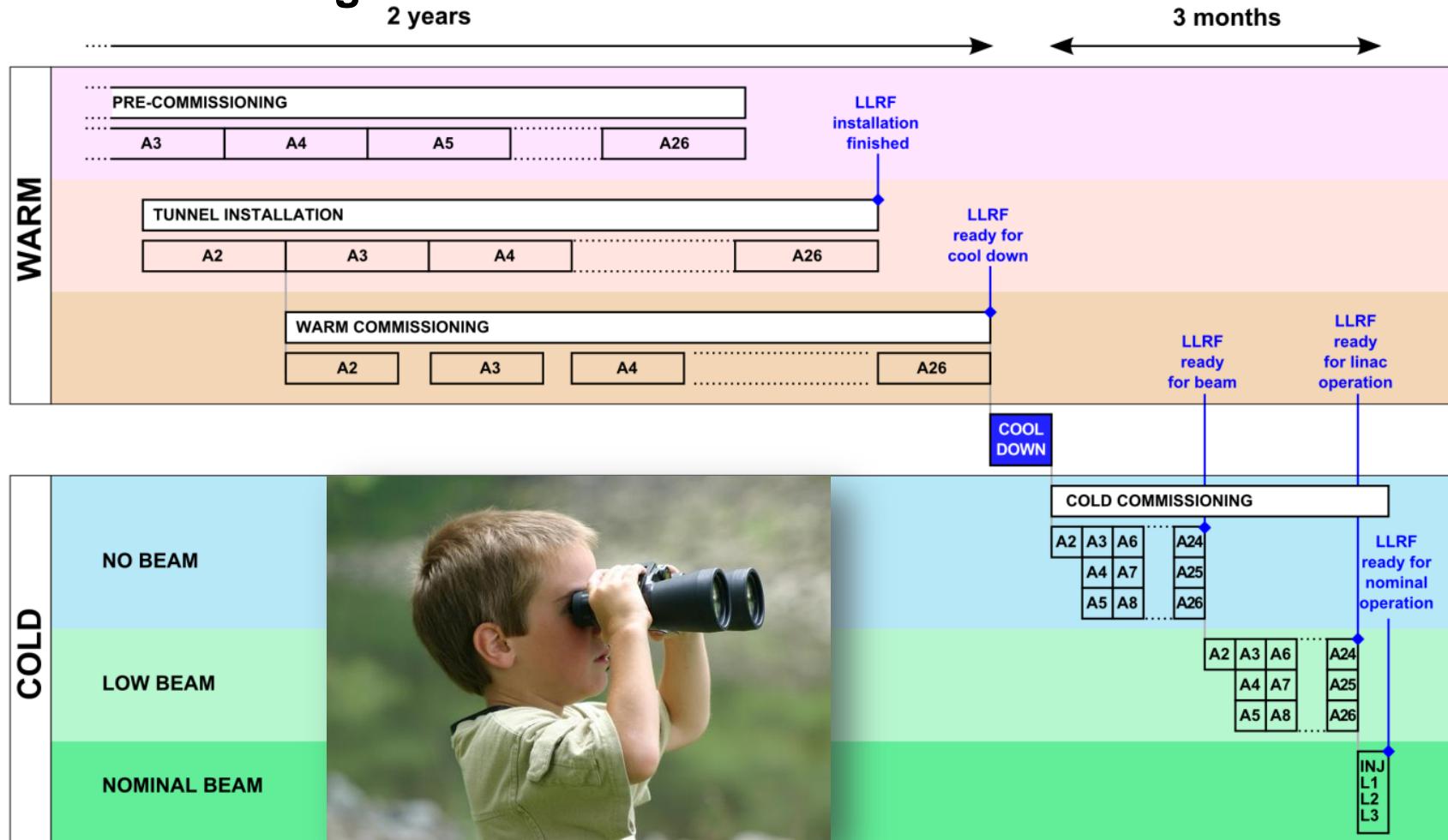
Main - ACC6									Main - ACC7									C1.ACC6									C2.ACC6								
C2.ACC7	C3.ACC7	C4.ACC7	C5.ACC7	C6.ACC7	C7.ACC7	C8.ACC7	C3.ACC6	C4.ACC6	C5.ACC6	C6.ACC6	C7.ACC6	C8.ACC6	C1.ACC7	C1.ACC6	C2.ACC6	C3.ACC6	C4.ACC6	C5.ACC6	C6.ACC6	C7.ACC6	C8.ACC6	C1.ACC7	C1.ACC6	C2.ACC6	C3.ACC6	C4.ACC6	C5.ACC6	C6.ACC6	C7.ACC6	C8.ACC6					
Move motor enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> Enable	<input type="checkbox"/> STOP																					
ALL ON	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>																				
ALL OFF	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>																				
QL SP	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000	000000						
Avg QL	2452647	2477117	2770227	2636500	2956047	2973049	2860477	2888423																											
QL error [%]	18.25	17.43	7.66	12.12	1.47	0.90	4.65	3.72																											
Motor status	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved	ready to be moved																			
Motor pos. SP	57872	276662	81992	167624	242252	913724	309002	194507																											
Motor current pos.	57872	276662	81992	167624	242252	913724	309002	194507																											

### Cavity resonance control



# LLRF FOR LARGE SCALE ACCELERATORS

## > Commissioning



# QUESTIONS?



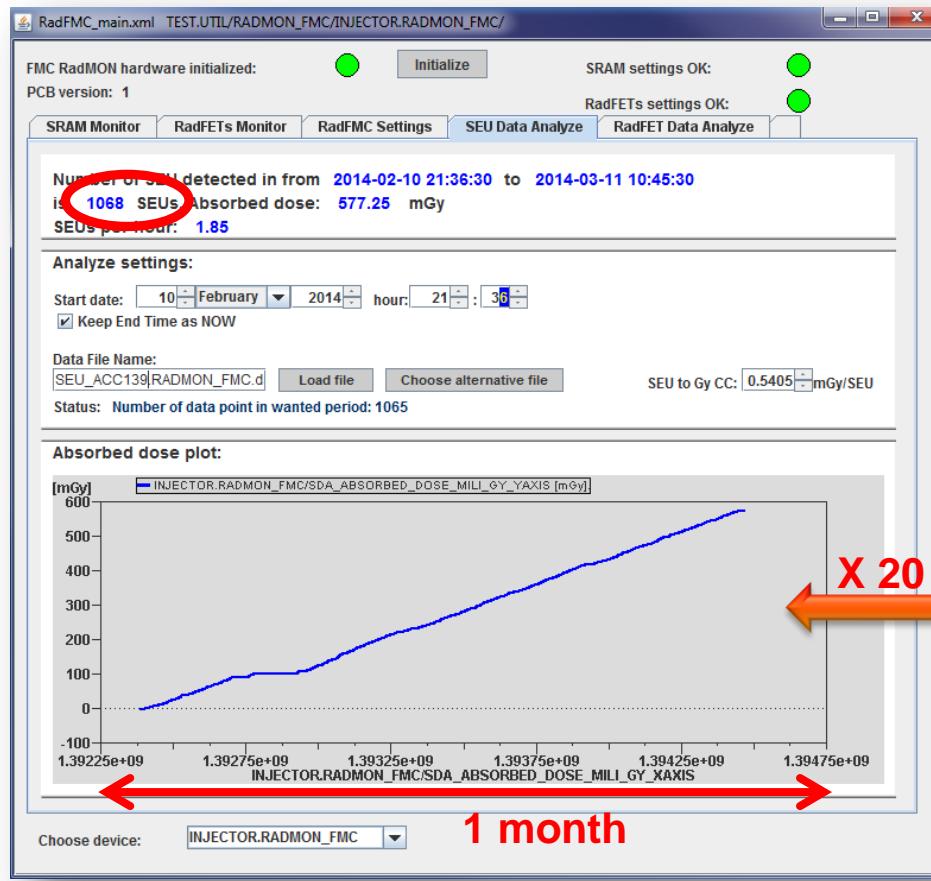
# BACK UP SLIDES



# RADIATION MEASUREMENTS : first results at FLASH

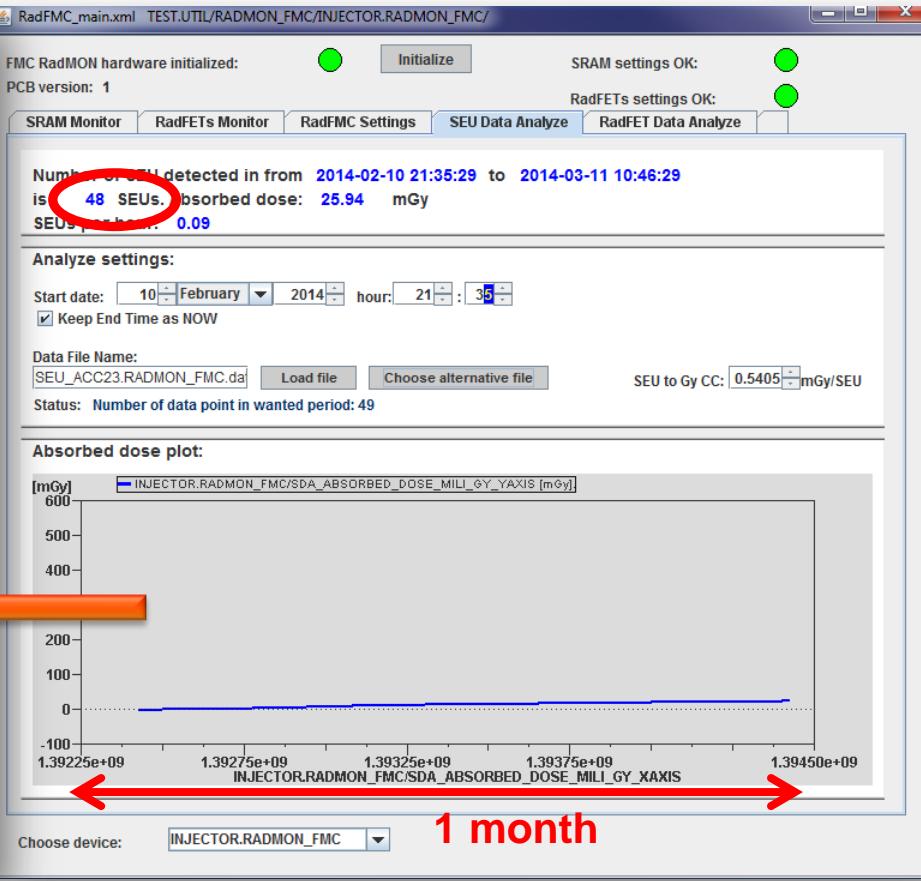
## > Counting Single Event Upsets (SEU) on SRAM

ACC1 / 39



1.85 SEU / hour

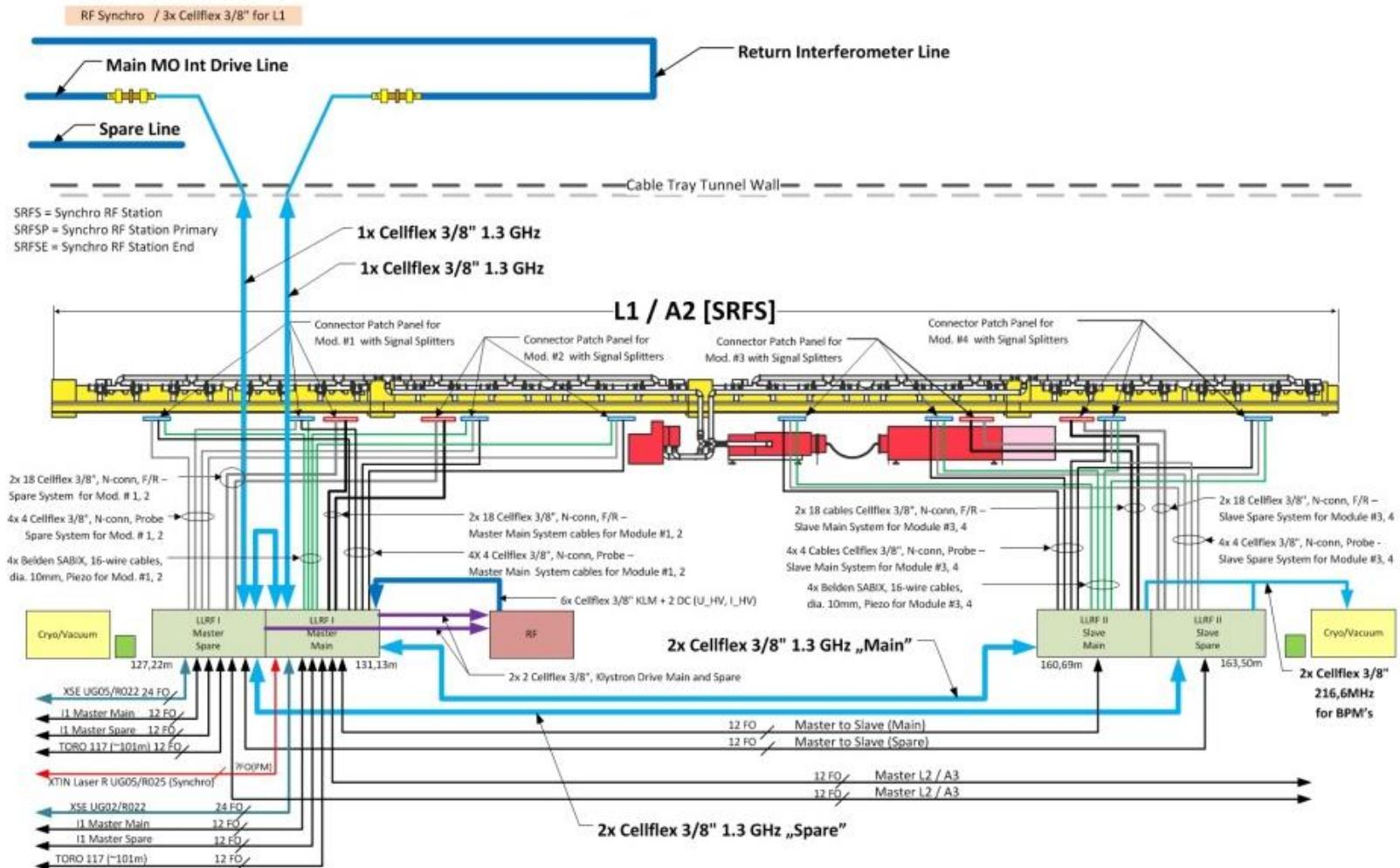
ACC23



0.09 SEU / hour

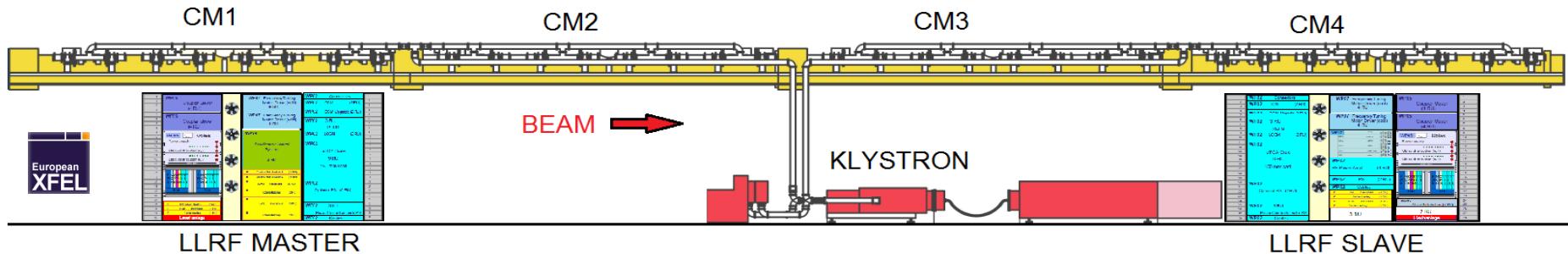
# LLRF FOR LARGE SCALE ACCELERATORS

## ➤ Large channel count



# HIGH LEVEL SERVERS (example)

## > INTRA-STATION communication



## > INTER-STATION communication

